

Navigating the Mazes of Autonomy and Embodiment in Cognitive Systems

David Vernon
University of Skövde
Sweden

www.vernon.eu

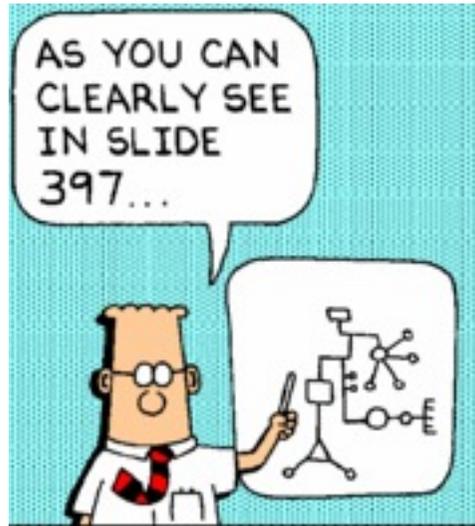
Xperience Summer School

Cala Millor

5 October 2013



HEALTH WARNING



DANGER

POISON 

HEALTH WARNING



*No videos,
Few images,
What are we waiting for!*



Cognitive System

“A **cognitive system** is an **autonomous** system that can **perceive** its environment, **learn** from experience, **anticipate** the outcome of events, **act** to pursue goals, and **adapt** to changing circumstances.”



[Vernon, Encyclopedia of Computer Vision, Springer, 2013]

Adaptive autonomy
Adjustable autonomy
Agent autonomy
Basic autonomy
Behavioural autonomy
Belief autonomy
Biological autonomy
Causal autonomy
Constitutive autonomy
Energy autonomy
Mental autonomy
Motivational autonomy
Norm autonomy
Robotic autonomy
Shared autonomy
Sliding autonomy
Social autonomy
Subservient autonomy
User autonomy

Autonomy



Adaptive autonomy	Ziemke 2008; Barandian 2004.
Adjustable autonomy	Bradshaw et al. 2004; Schillo 2002.
Agent autonomy	Hexmoor, Castelfranchi, Falcone 2003.
Basic autonomy	Ruiz-Mirazo and Moreno 2004.
Behavioural autonomy	Froese, Virgo, Izquierdo 2007.
Belief autonomy	Barber and Park 2004.
Biological autonomy	Varela 1979; Di Paolo 2004; Ziemke 2008.
Causal autonomy	Bertschinger, Olbrich, Ay, and Jost 2008.
Constitutive autonomy	Froese, Virgo, Izquierdo 2007; Froese and Ziemke 2009
Energy autonomy	Ieropoulos et al. 2012. Ziemke and Lowe 2009.
Mental autonomy	Ziemke and Lowe 2009.
Motivational autonomy	Ziemke and Lowe 2009.
Norm autonomy	Carabelea et al. 2004; Castelfranchi & Falcone 2004.
Robotic Autonomy	Ziemke 2008; Moreno, Etxeberria, Umerez 2008.
Shared autonomy	Pitzer et al. 2011.
Sliding autonomy	Sellner et al. 2006.
Social autonomy	Carabelea, Boissier, Florea 2004.
Subservient autonomy	Meystel 2000
User autonomy	Carabelea, Boissier, Florea 2004.

Embodiment



Historical embodiment
Physical embodiment
Organismoid embodiment
Organismic embodiment
Social embodiment
Mechanistic embodiment
Phenomenal embodiment

Embodiment



Embodied cognition
Situated cognition
Embedded cognition
Grounded cognition
Extended cognition
Distributed cognition

Anderson 2003; Shapiro 2007; Shapiro 2011	Embodied cognition
Clancey 1997; Robbins and Aydede 2008	Situated cognition
Wilson and Foglia 2012	Embedded cognition
Barsalou 2008; Barsalou 2010	Grounded cognition
Clark and Chalmers 1998; Clark 2008; Fodor 2009	Extended cognition
Hutchins 1995; Hollan, Hutchins, Kirsh 2000	Distributed cognition

Autonomy

Autonomy:

The degree of self-determination of a system

The degree to which

- A system's behaviour is **not determined** by the environment
- The degree to which a system determines its **own goals**

An autonomous system

is not controlled by some external agency

but is self-governing and self-regulating

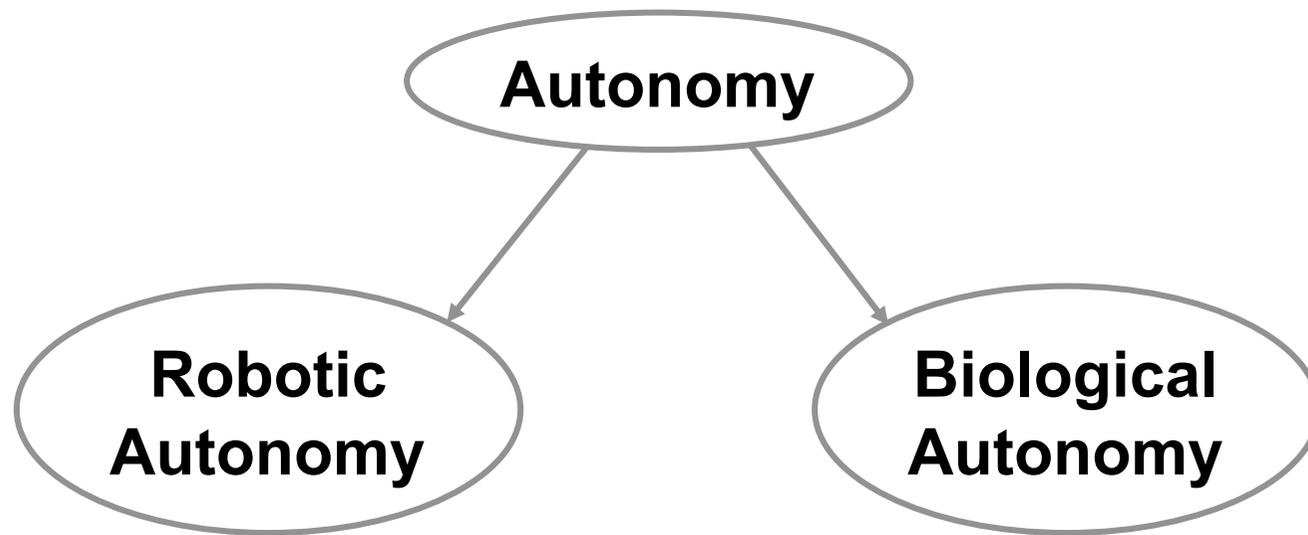
to a greater or lesser extent

An autonomous system

is not controlled by some external agency

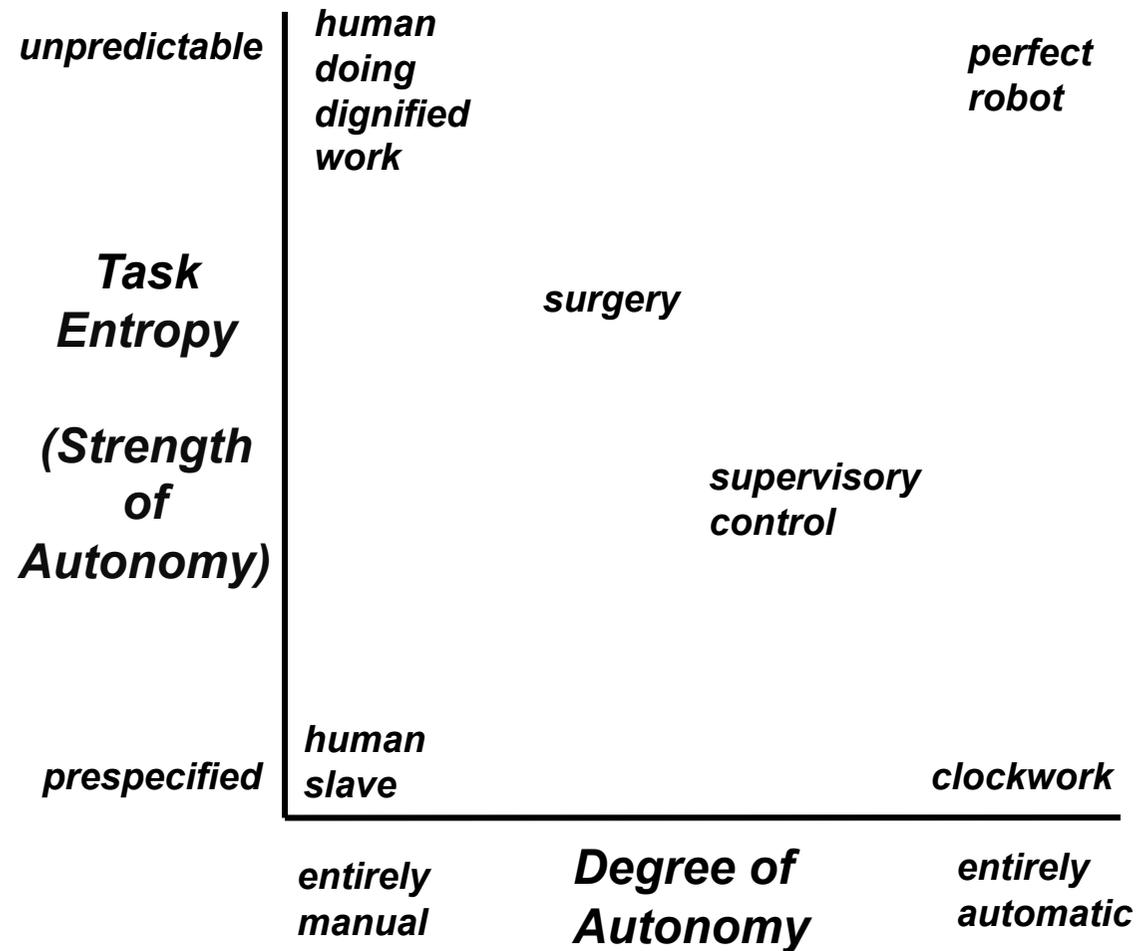
but is self-governing and self-regulating

to a greater or lesser extent



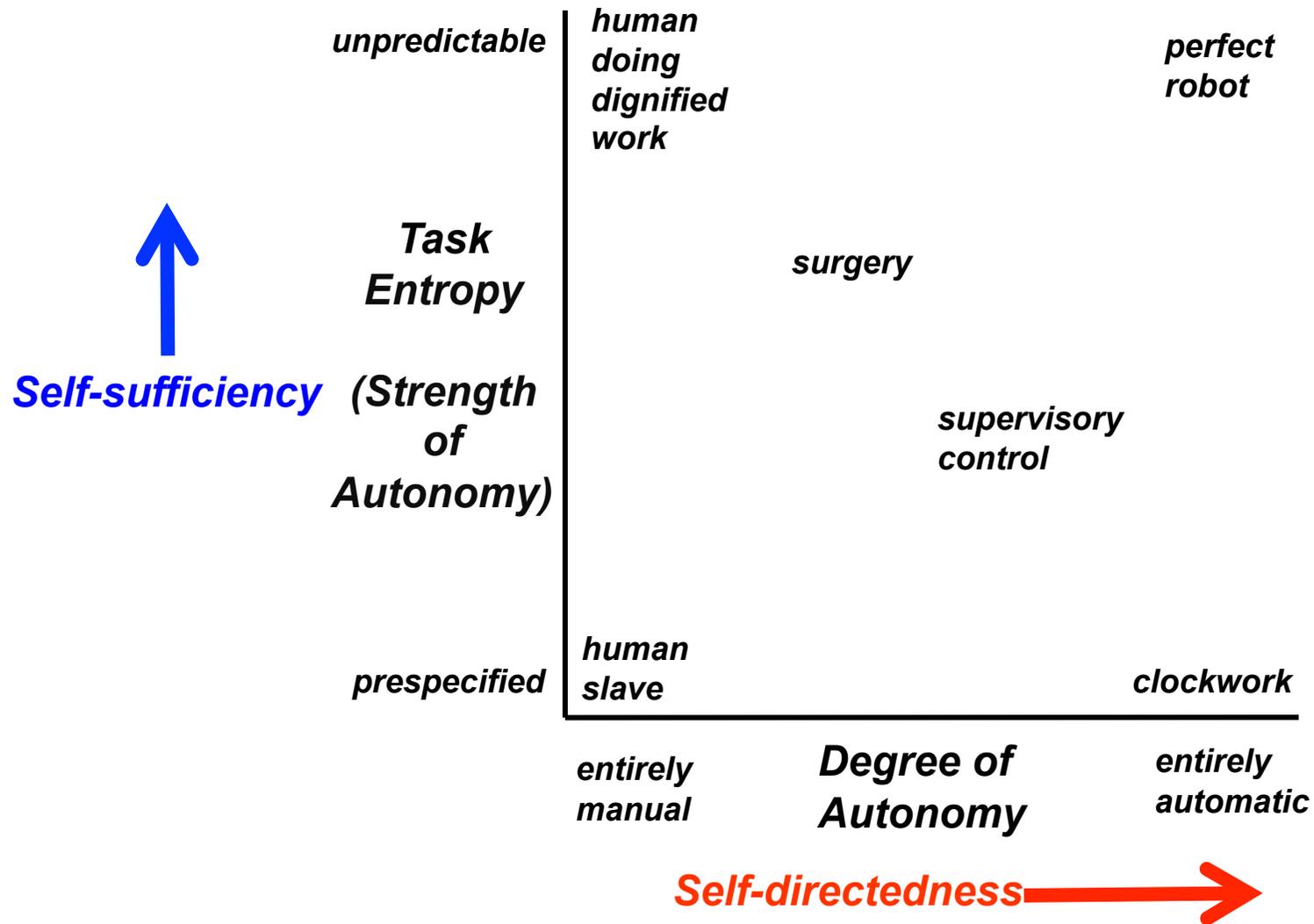
Robotic Autonomy

Robotic Autonomy

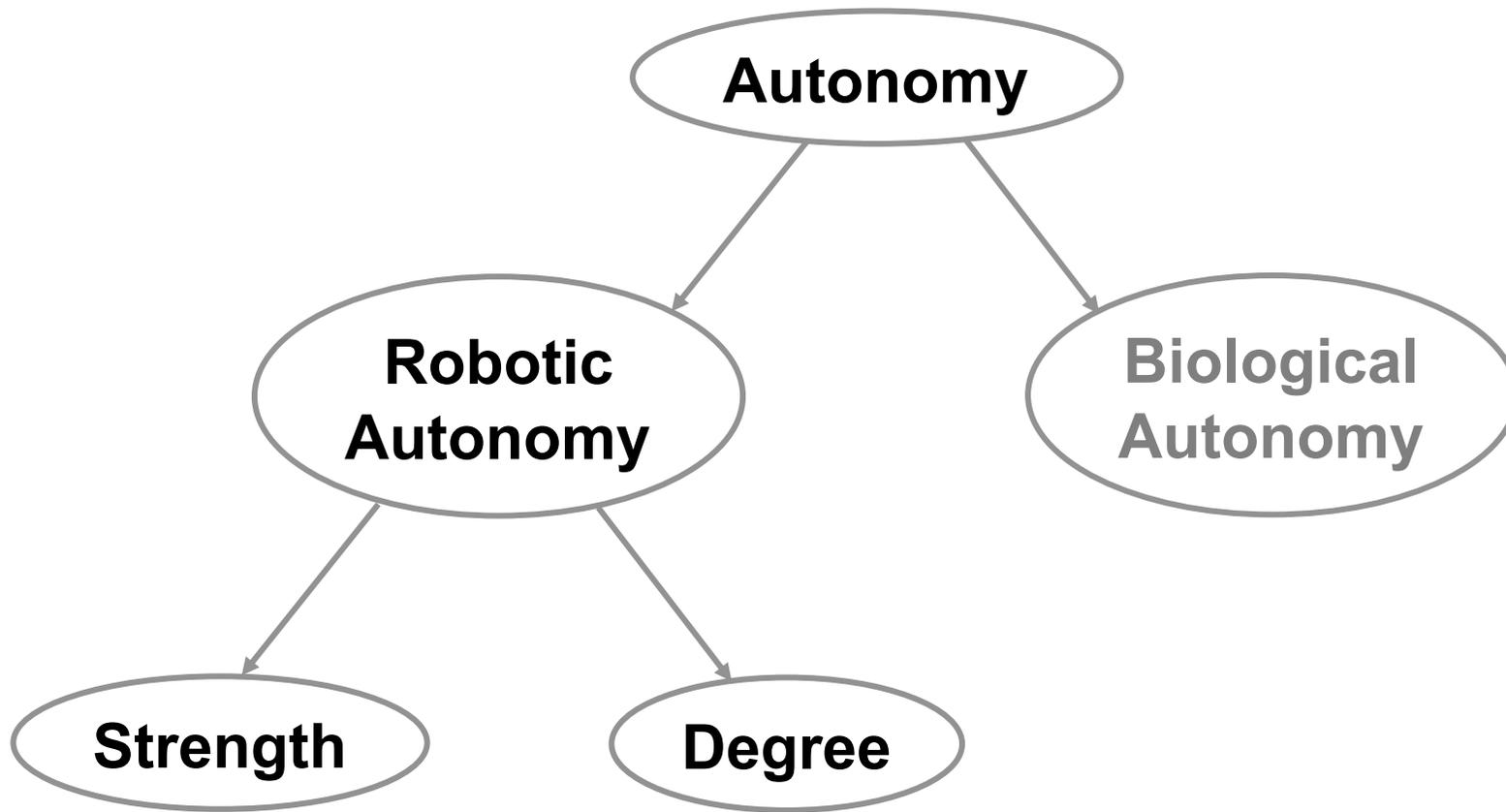


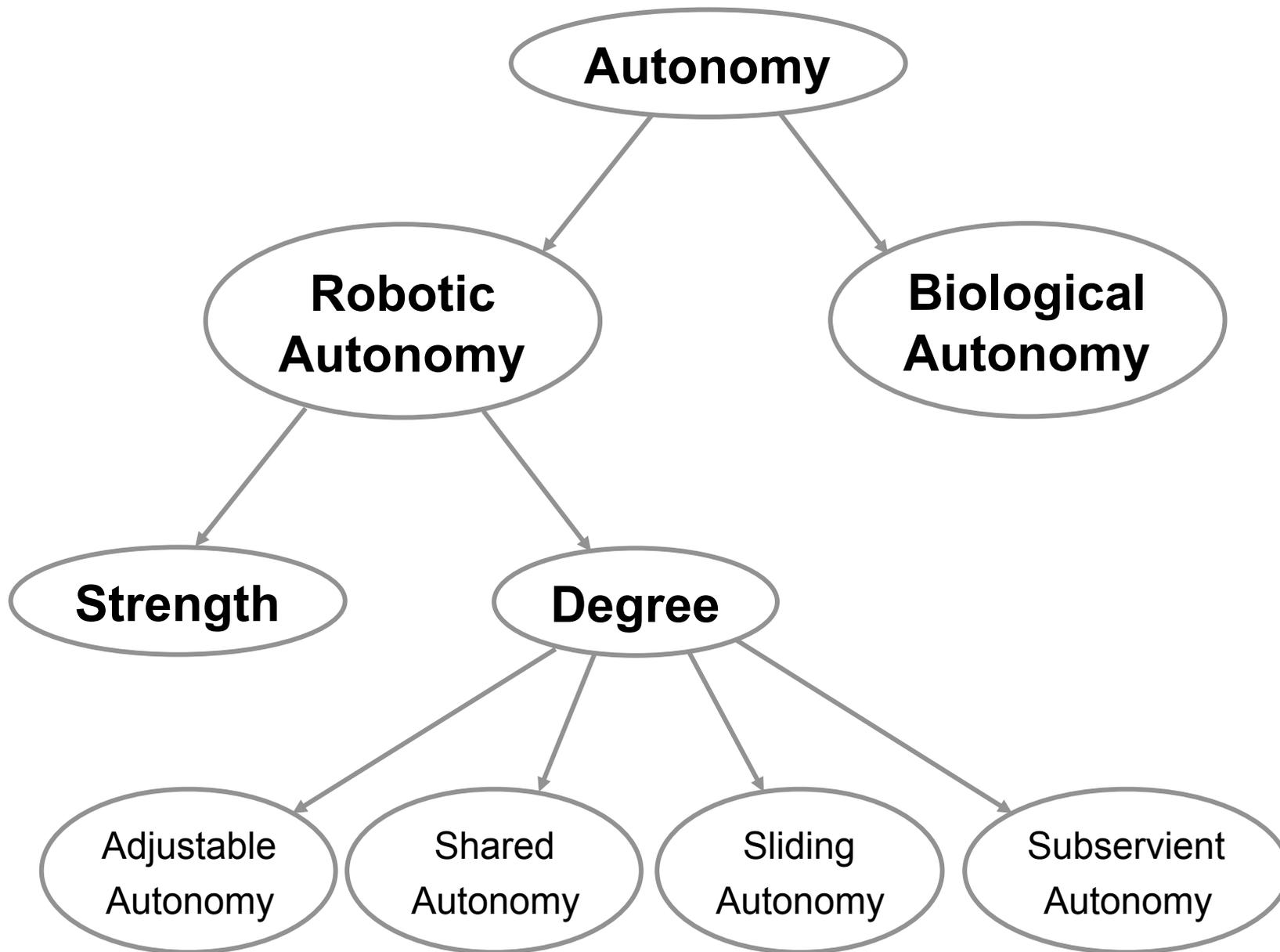
T. B. Sheridan and W. L. Verplank. Human and computer control for undersea teleoperators. Technical report, MIT Man-Machine Systems Laboratory, 1978.

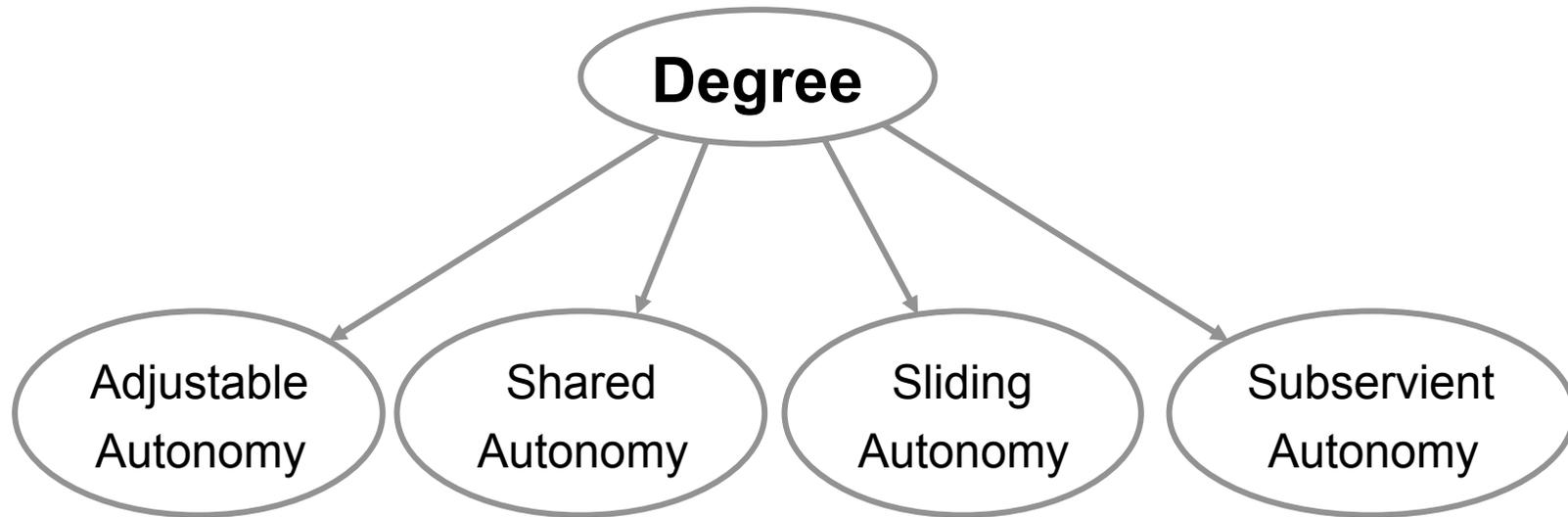
Robotic Autonomy



T. B. Sheridan and W. L. Verplank. Human and computer control for undersea teleoperators. Technical report, MIT Man-Machine Systems Laboratory, 1978.



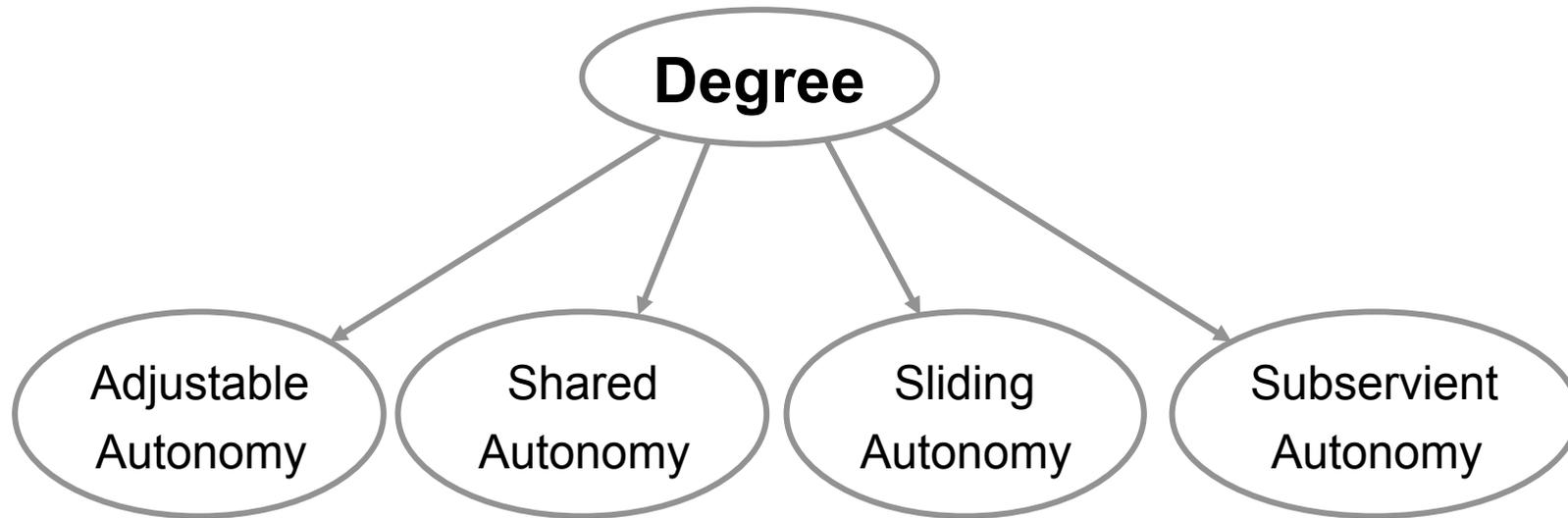




The system controls its own behaviour to a greater or lesser extent

BUT

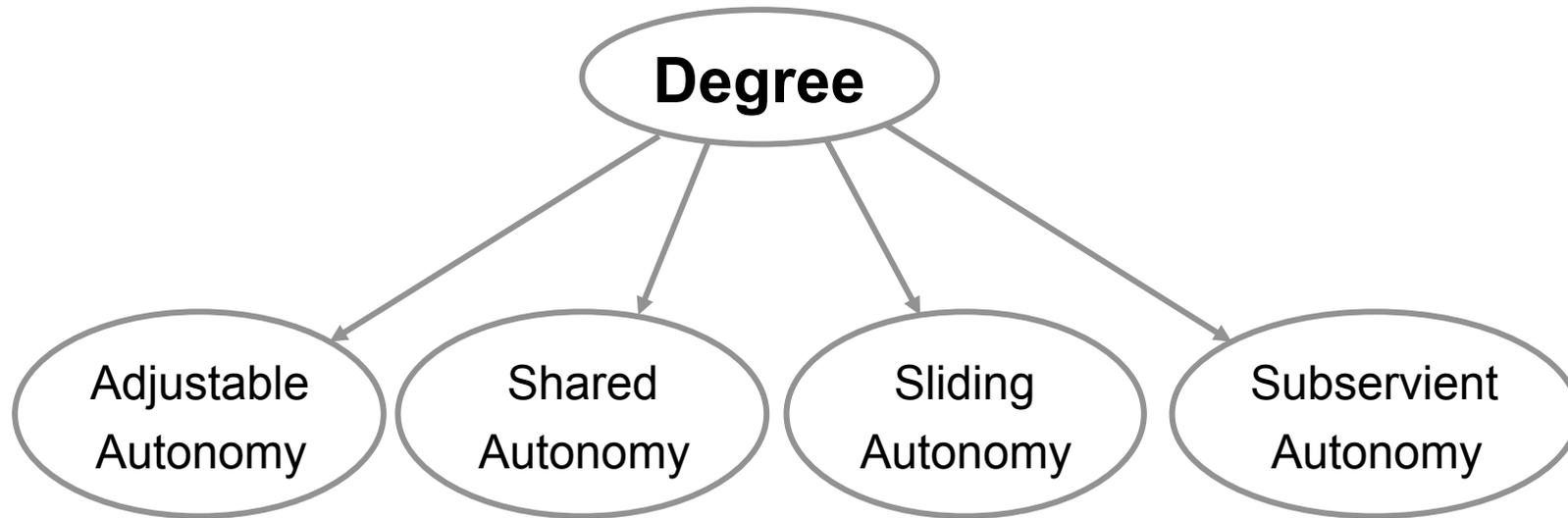
The goals are determined by the human with which it is interacting



Usually assign high-level functions to the human and lower-level functions to the autonomous agent

BUT

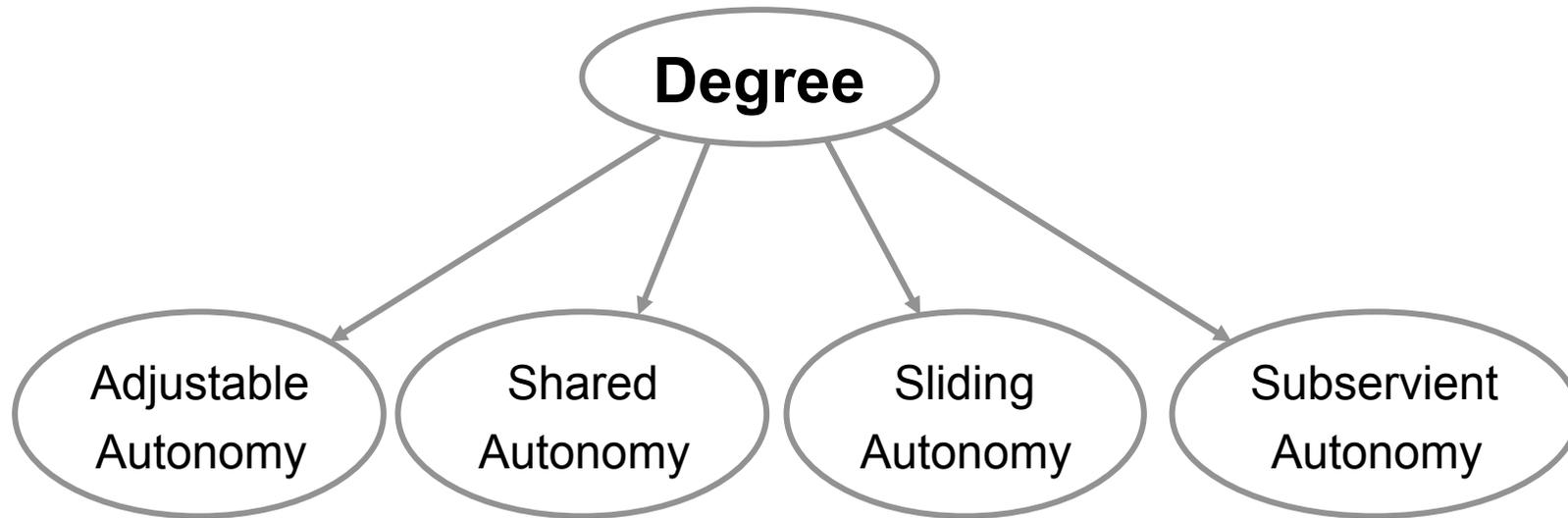
Sometimes the human intervenes when some difficult low-level operation is needed (e.g. visual interpretation) effectively



Issues, especially working with team of robots

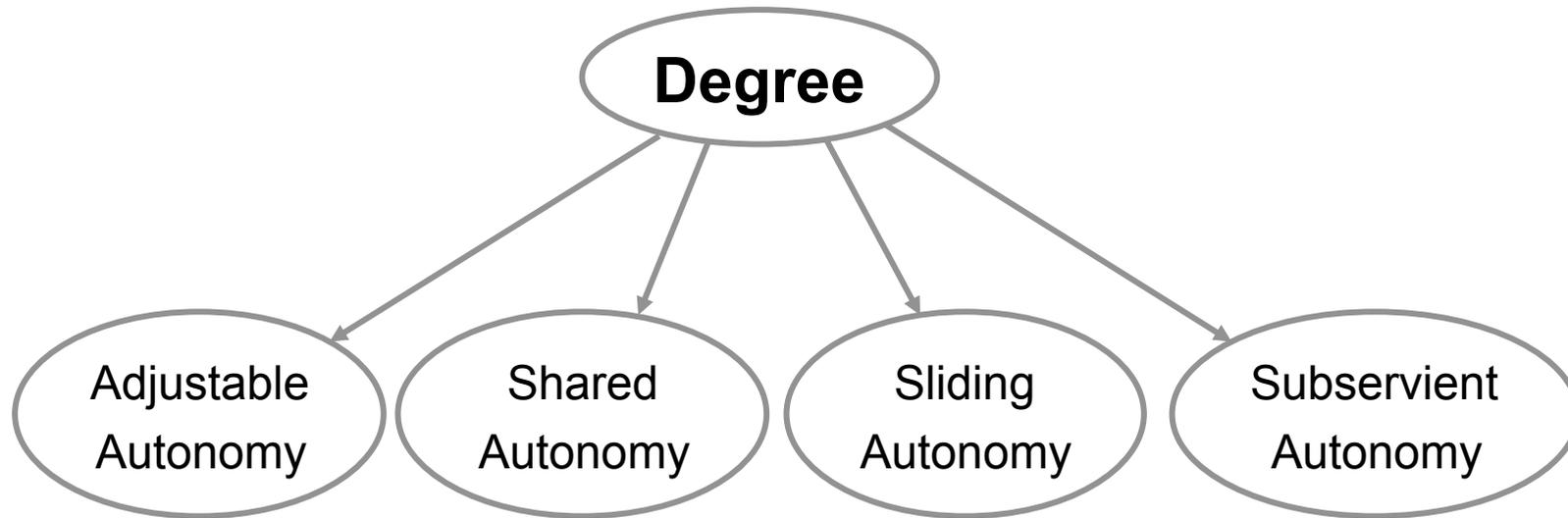
- The human operator may not always be aware of everything that is happening

... the robot may have to ask for help



Issues, especially working with team of robots

- The human will take time to assess the situation
... the robot needs to take account of this

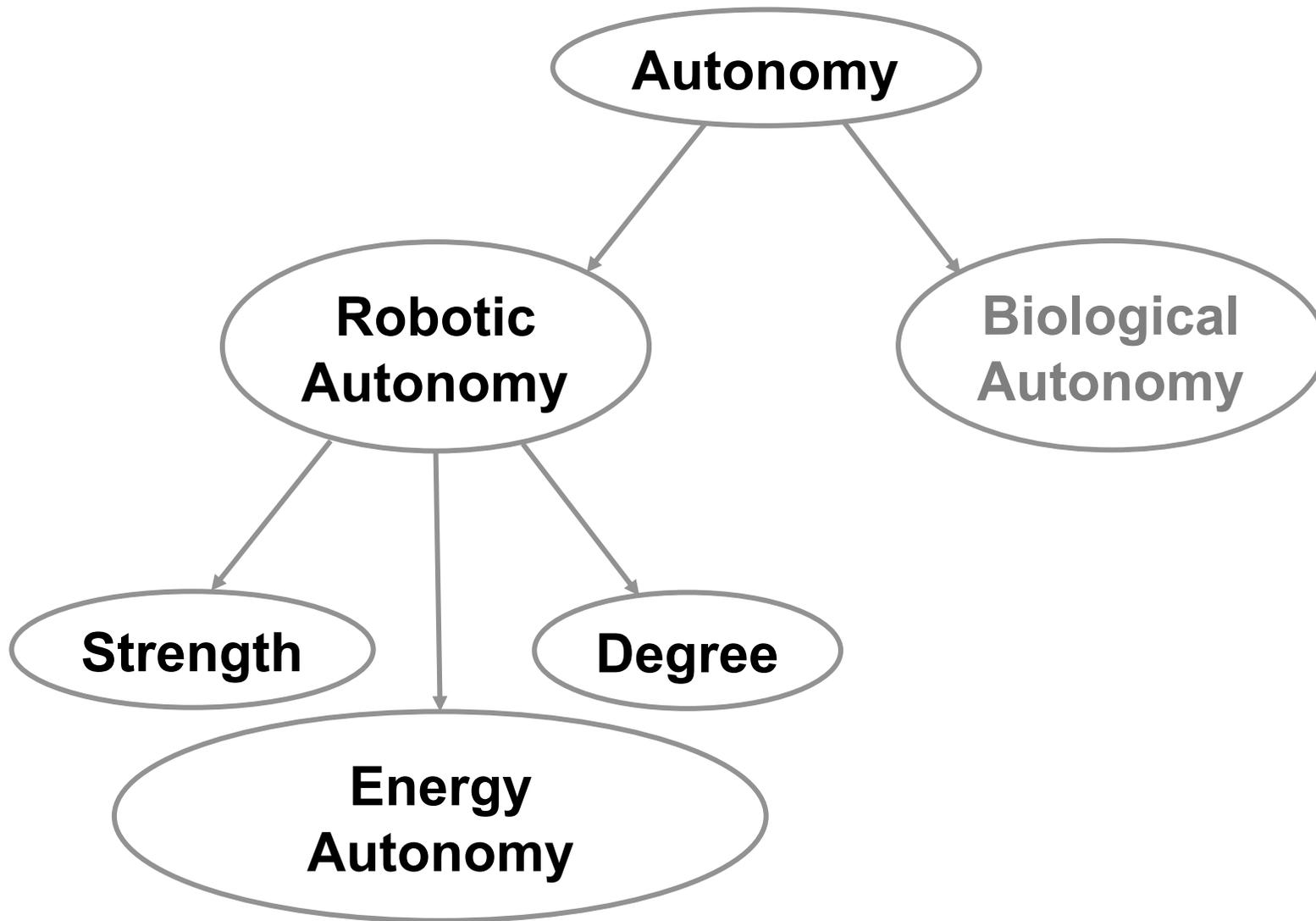


Issues, especially working with team of robots

- When the human does take control of a robot
 - ... the other robots in the team still have to work together effectively

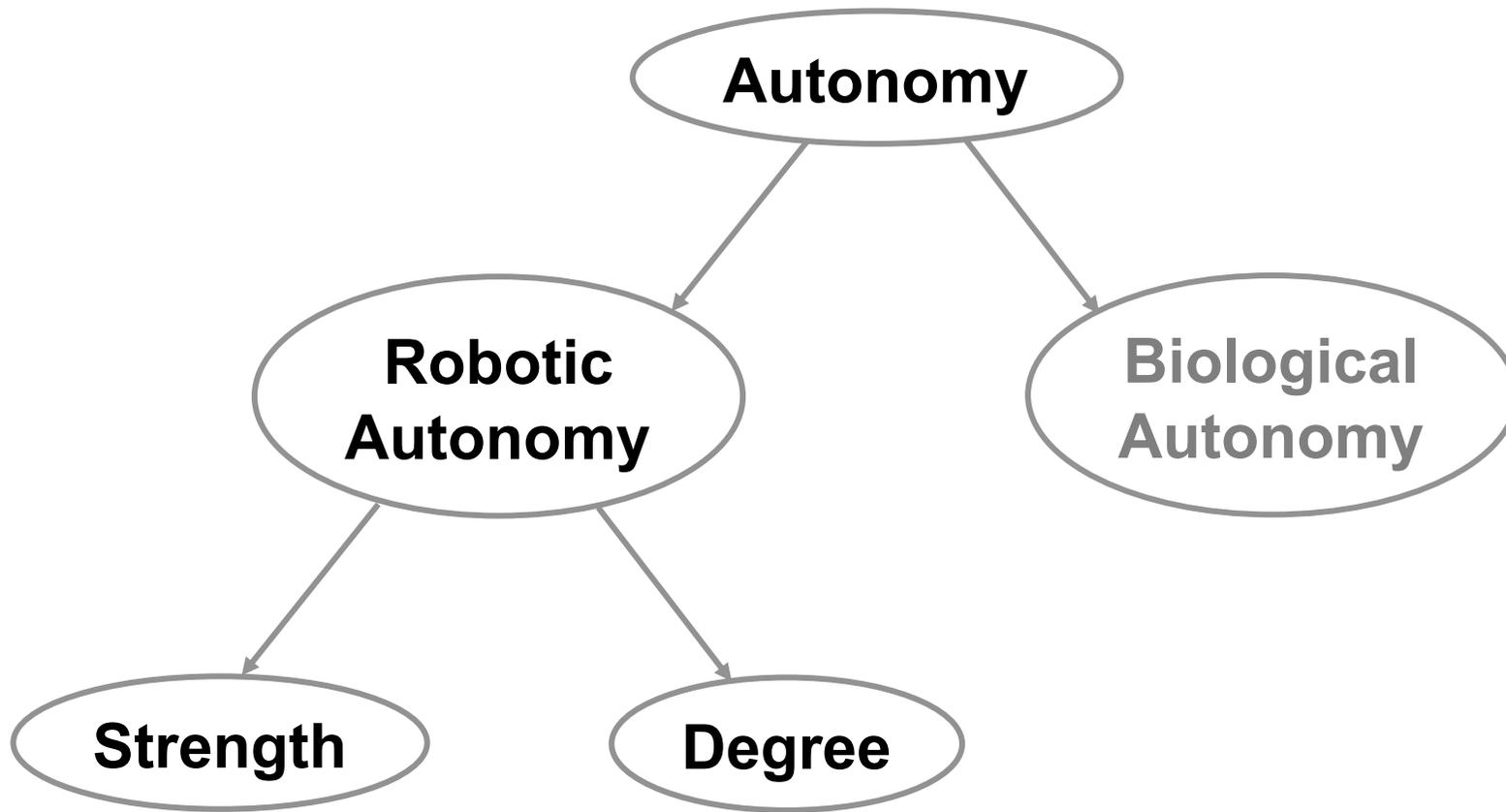
Characterization of shared responsibility

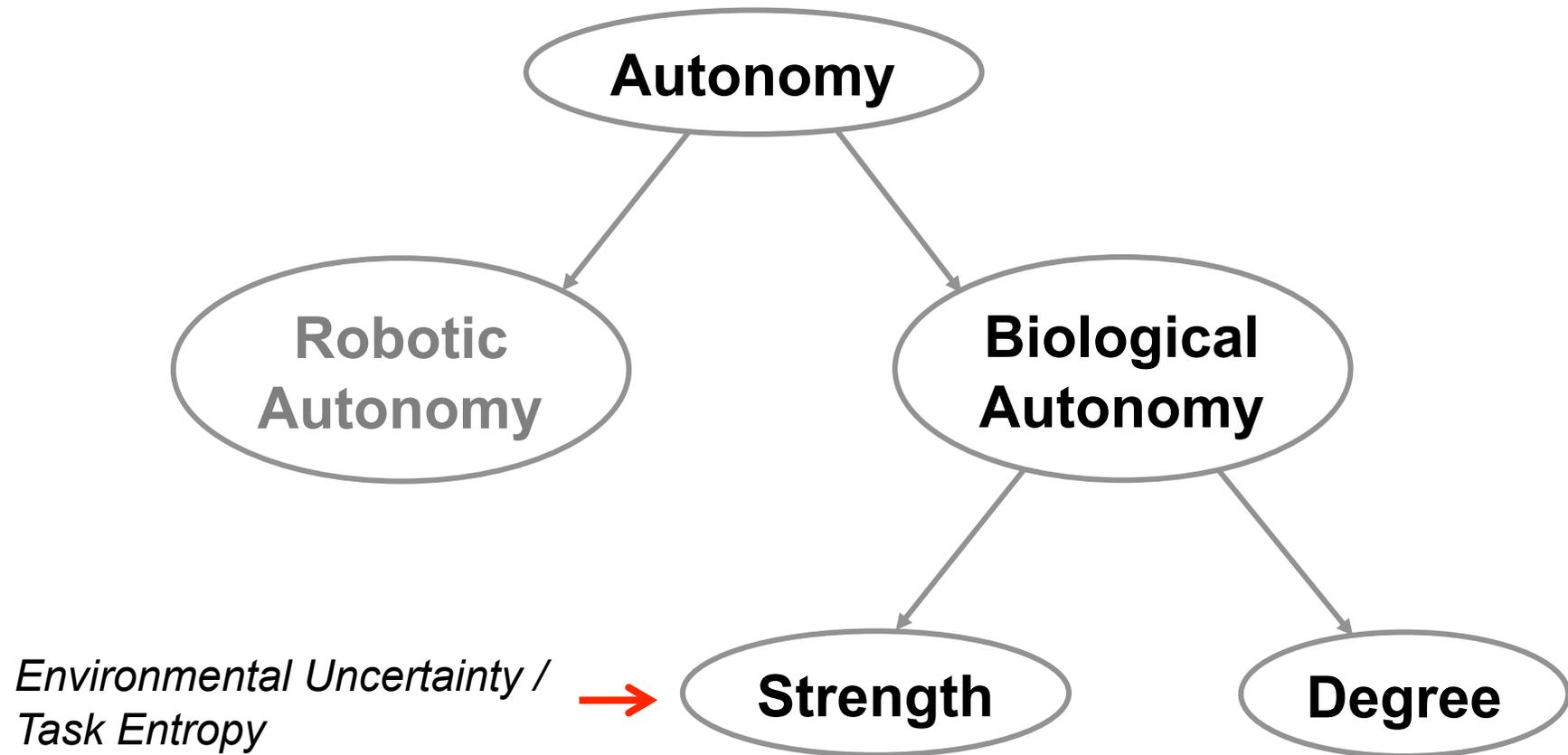
1. The human does the whole job up to the point of turning it over to the computer to implement
2. The computer helps by determining options
- ...
10. The computer does whole job if it decides it should be done, and if so tells human, if it decides he should be told



The robot can operate for extended periods of time without being connected to an external power outlet

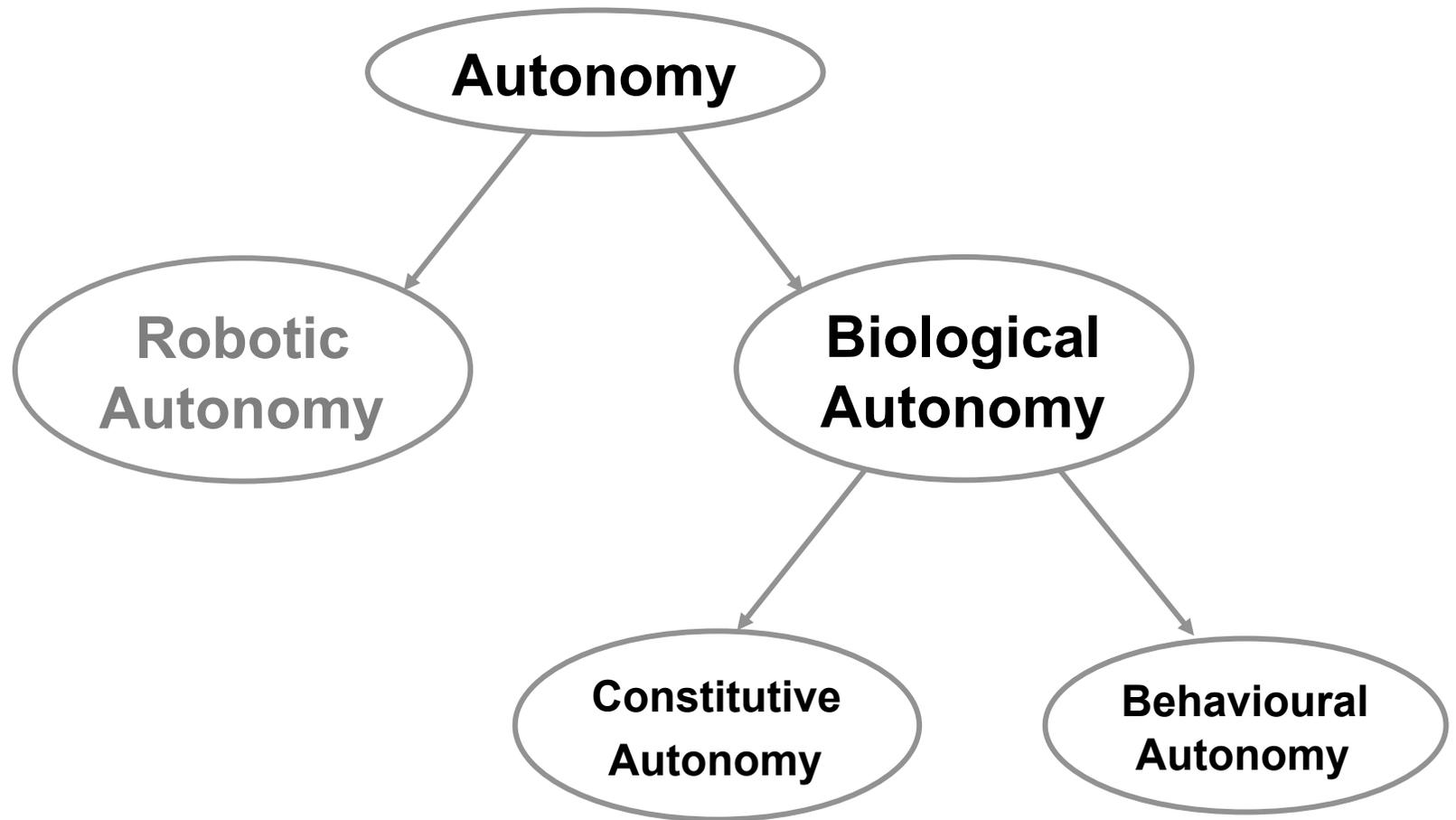
Biological Autonomy

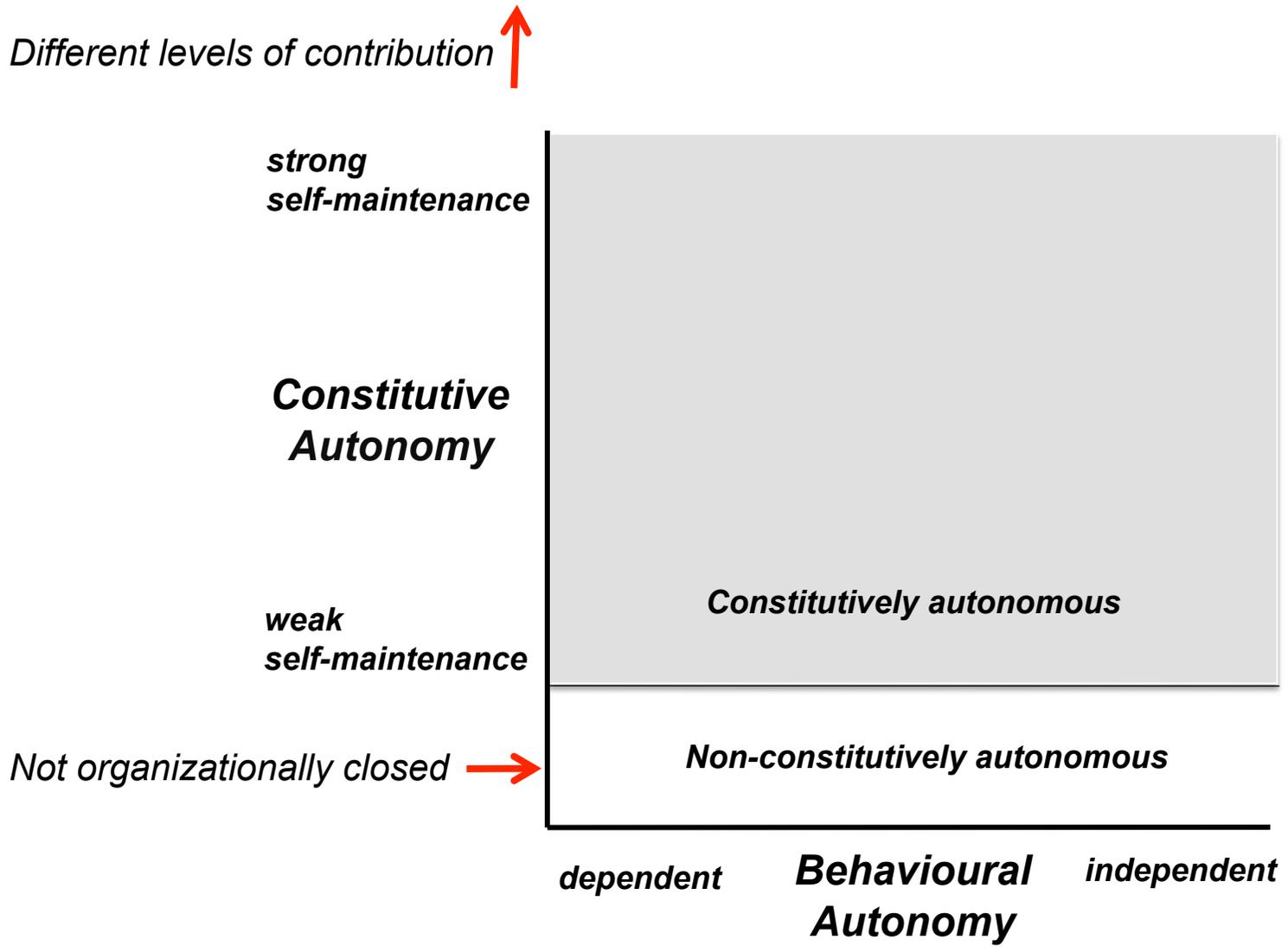




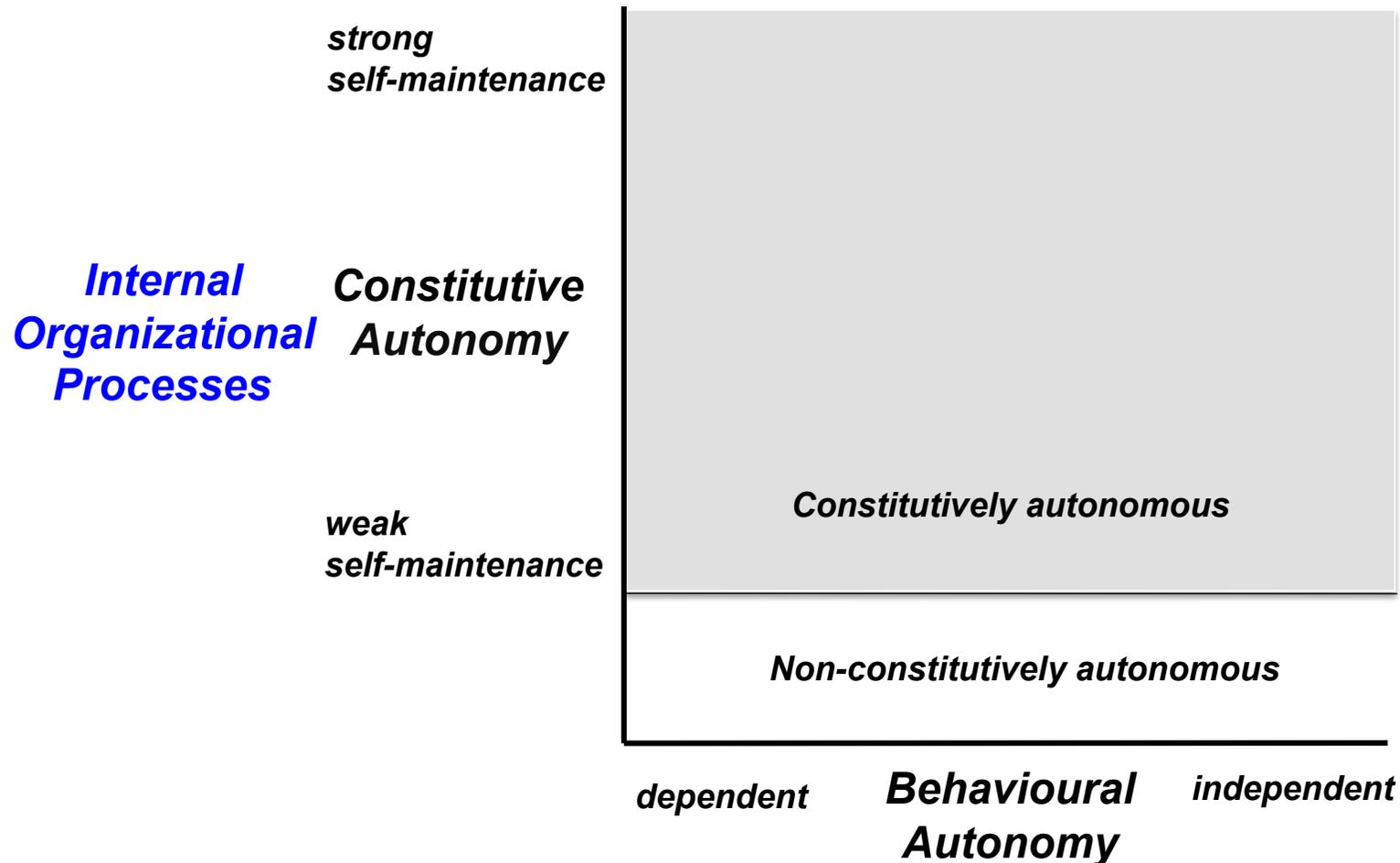
The issue of autonomy is one of survival, in the face of **precarious** conditions

... physically and organizationally as a dynamic self-sustaining entity.



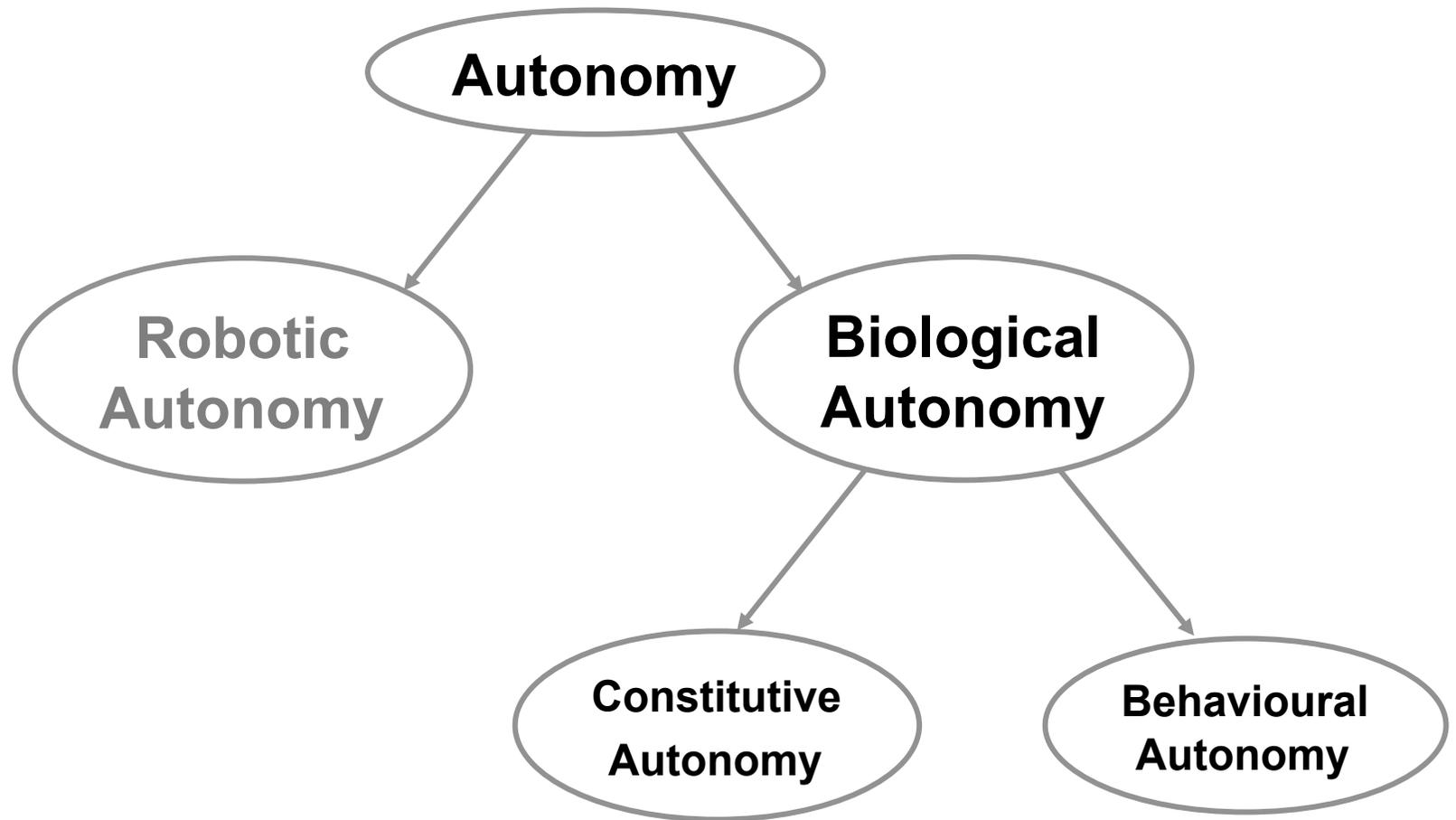


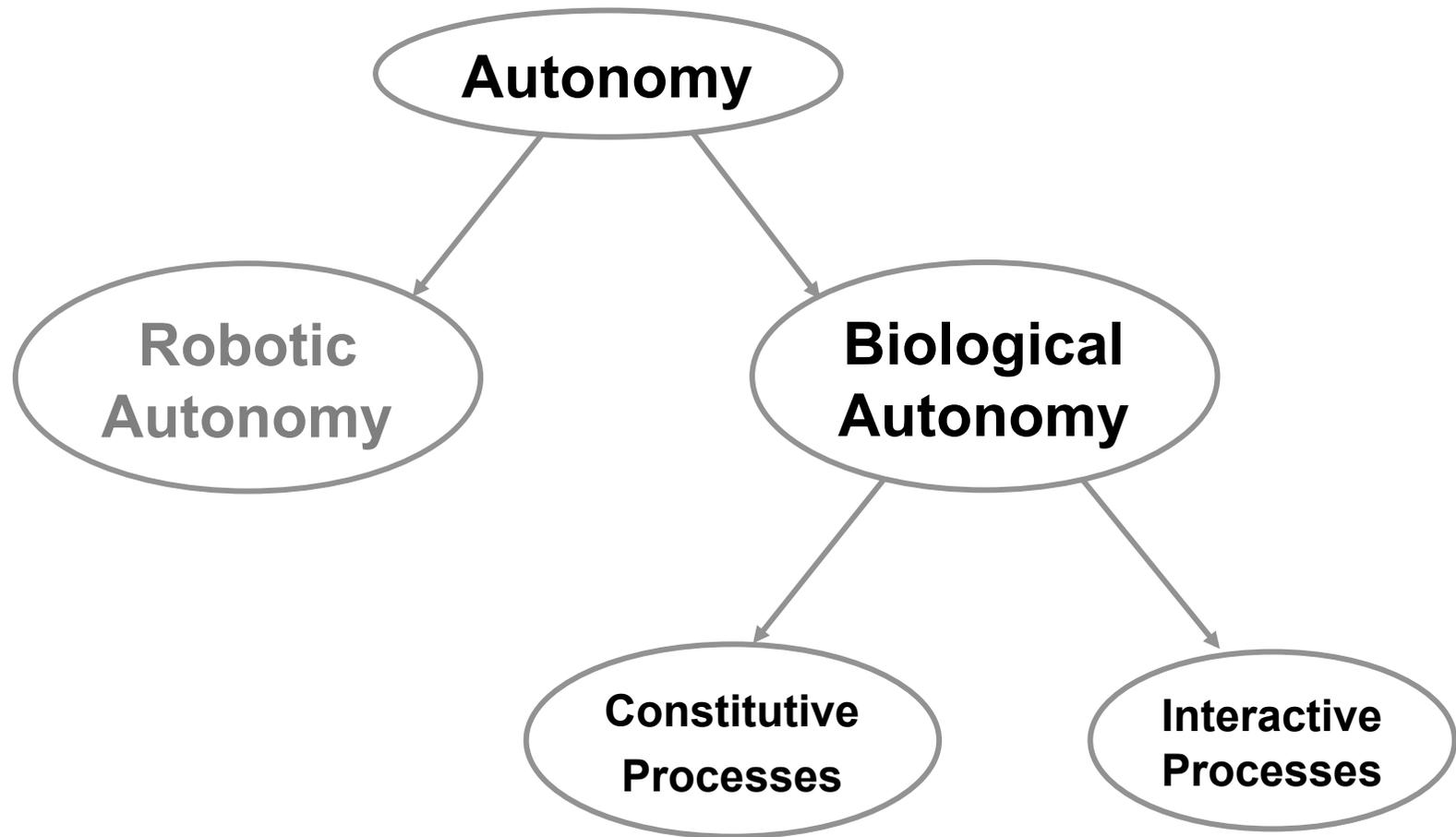
T. Froese, N. Virgo, and E. Izquierdo. Autonomy: a review and a reappraisal. In F. Almeida Costa et al. ,editors, Proceedings of the 9th European Conference on Artificial Life: Advances in Artificial Life, volume 4648, pages 455–465. Springer, 2007.



External Aspects: independent goals in precarious environment

T. Froese, N. Virgo, and E. Izquierdo. *Autonomy: a review and a reappraisal*. In F. Almeidae Costa et al. ,editors, *Proceedings of the 9th European Conference on Artificial Life: Advances in Artificial Life*, volume 4648, pages 455–465. Springer, 2007.

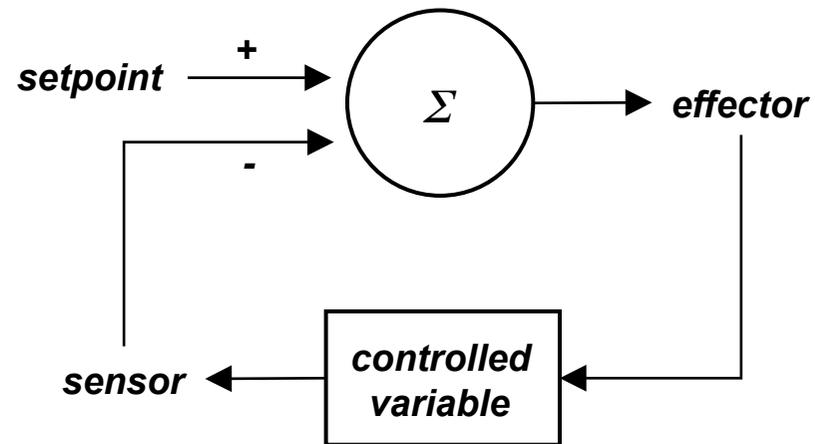




Self-construction, self-regulation, & self-repair;
faster time-scales to interaction processes

Key processes: Homeostasis & Allostasis

Homeostasis



Homeostasis: the automatic regulation of physiological functions

Walter Cannon in 1929: “Organization for Physiological Homeostasis”

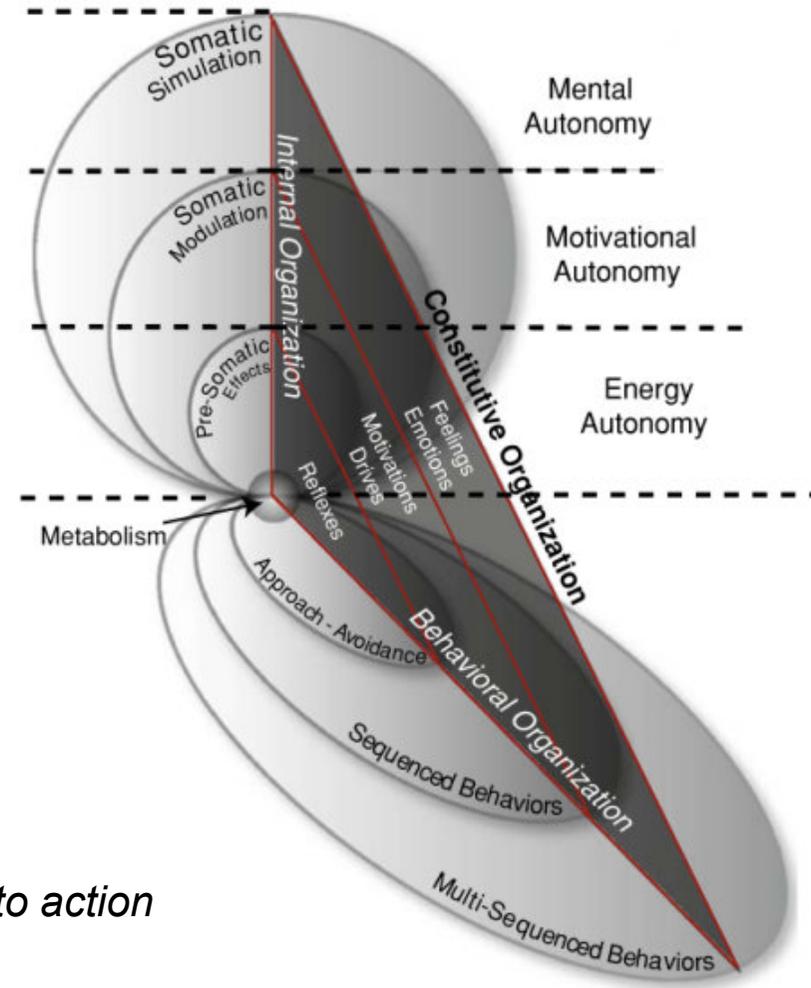
Goal: **stability through constancy**: set point & negative feedback

The Cognitive-Affective Architecture Schematic

Constitutive Organization

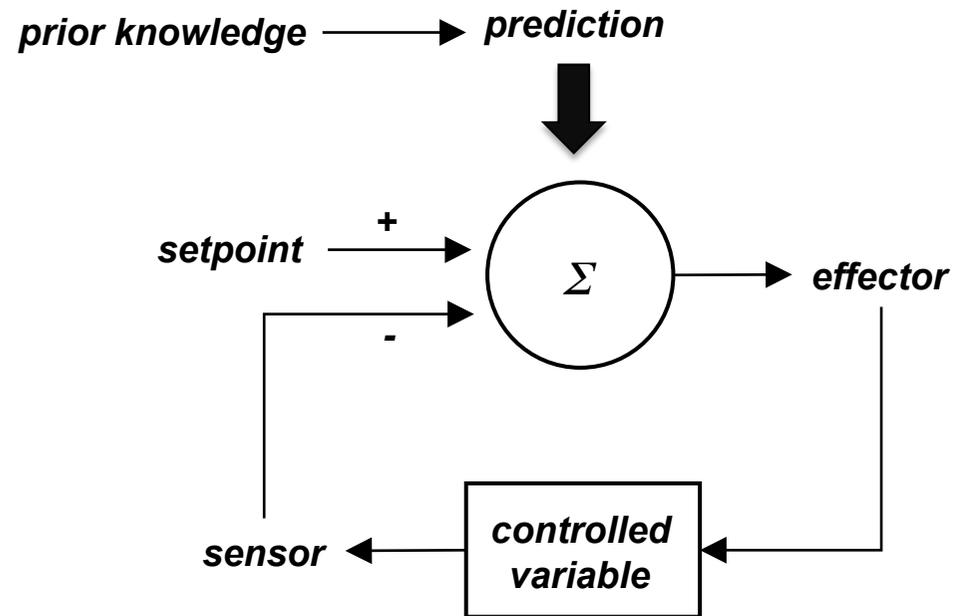
Each level is associated on the Internal Organization axis with an increasing level of **homeostatic** autonomy-preserving self-maintenance:

- a) Basic metabolic processes
- b) Reactive sensorimotor activity (pre-somatic effects)
- c) Associative learning and prediction (somatic modulation)
- d) Interoception and internal simulation of behaviour prior to action



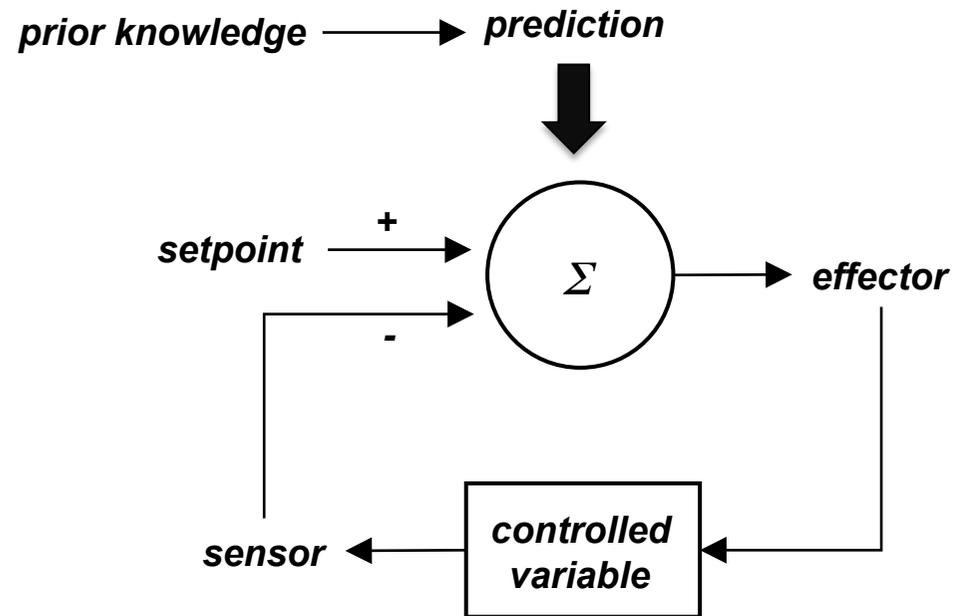
A. Morse, R. Lowe, and T. Ziemke. Towards an enactive cognitive architecture. In *Proceedings of the First International Conference on Cognitive Systems*, Karlsruhe, Germany, 2008.

Allostasis



Homeostasis: adjusting to an event

Allostasis: adjusting before an event occurs

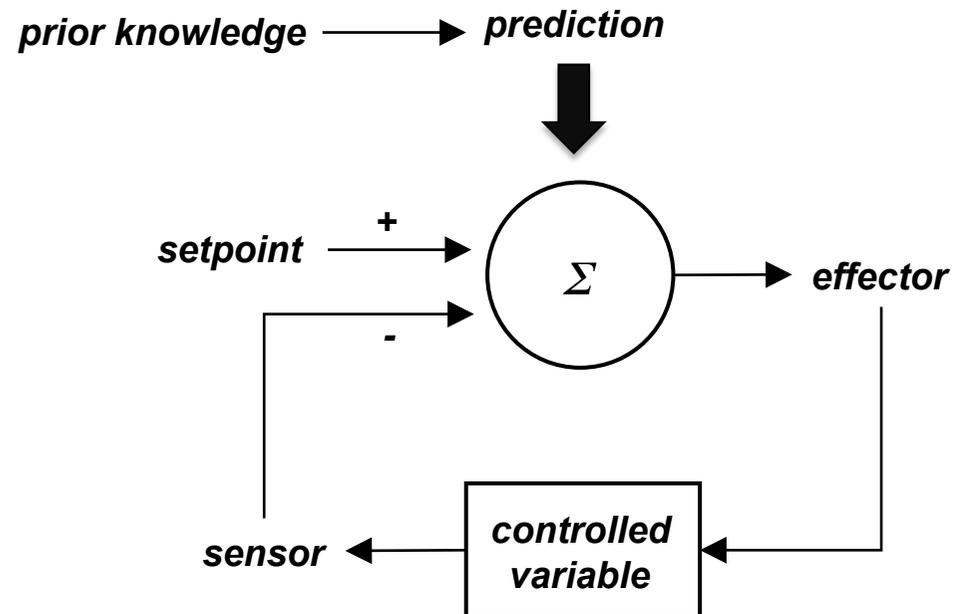


Continual preparation for what might be coming next

Anticipates events, actively prepares

Predictive self-regulation vs. reactive self-regulation

Ready themselves for multiple contingencies



Use priors to anticipate the likely demands that will be placed on the system

Pre-emptively adjust all the parameters to meet this demand

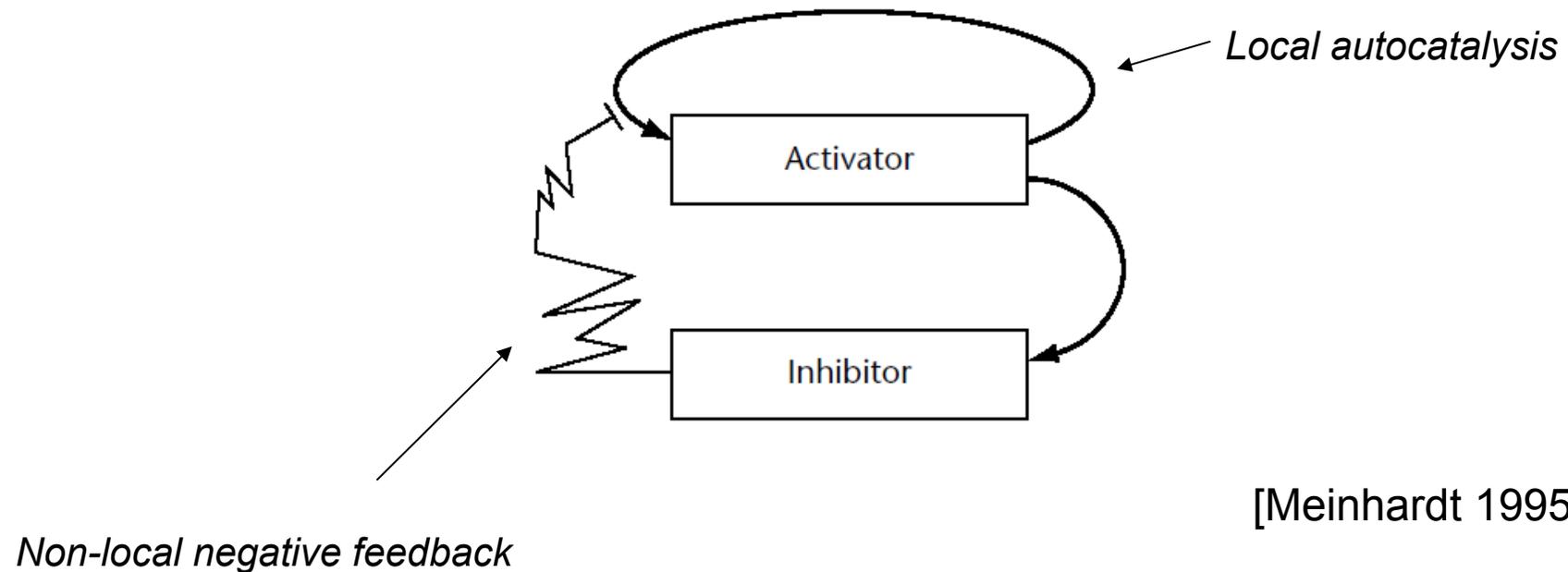
Goal: **stability through change** ... change the controlled variable by predicting what value will be needed and **overriding** local feedback to meet anticipated demand

Self-organization & Emergence

Self-organization

“Pattern and structure at the global level arises solely from interactions among the lower-level components of the system ... without reference to the global pattern.”

[Camazine 2006]

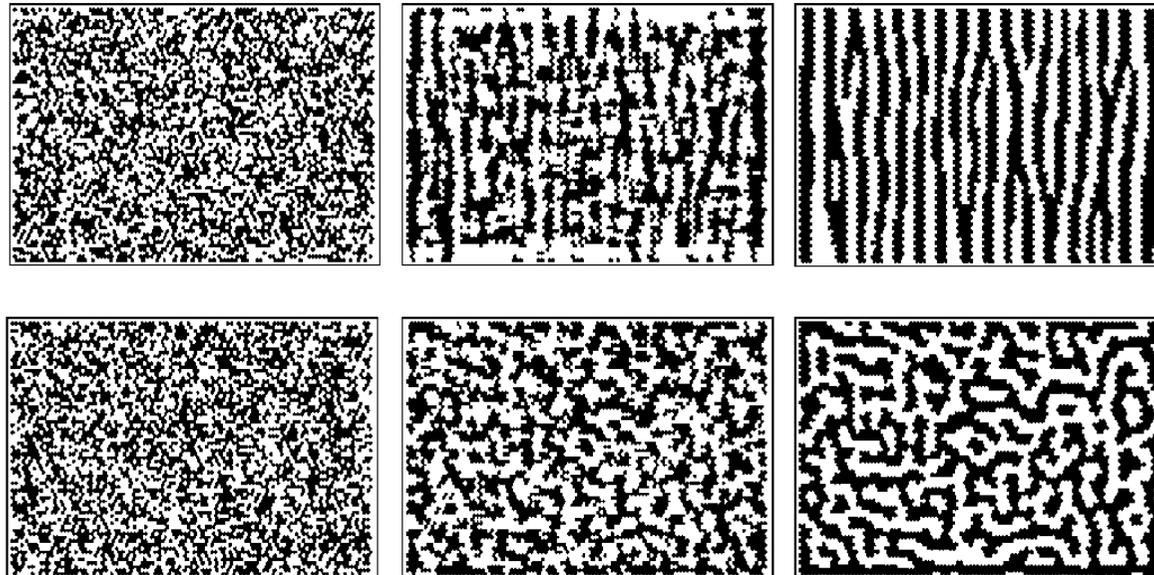


[Meinhardt 1995]

Self-organization

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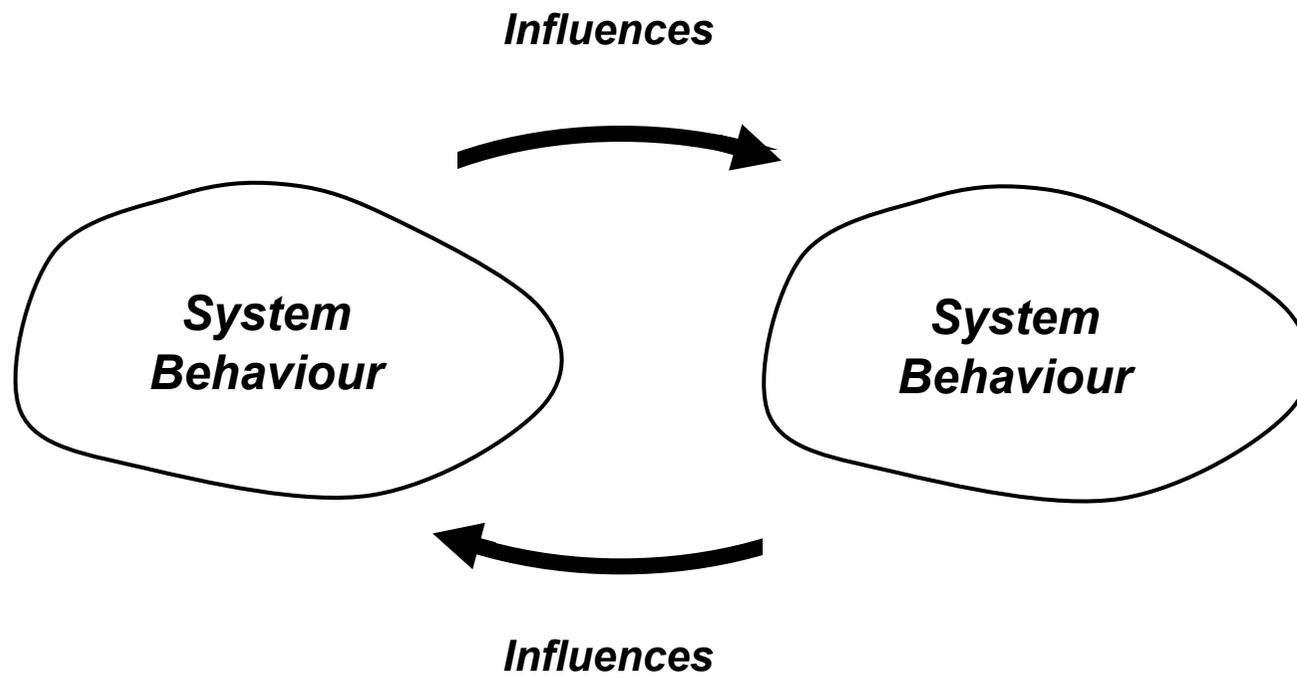
Emergence

“A process by which a system of interacting elements acquires qualitatively new pattern and structure that **cannot be understood simply as the superposition of the individual contributions**”

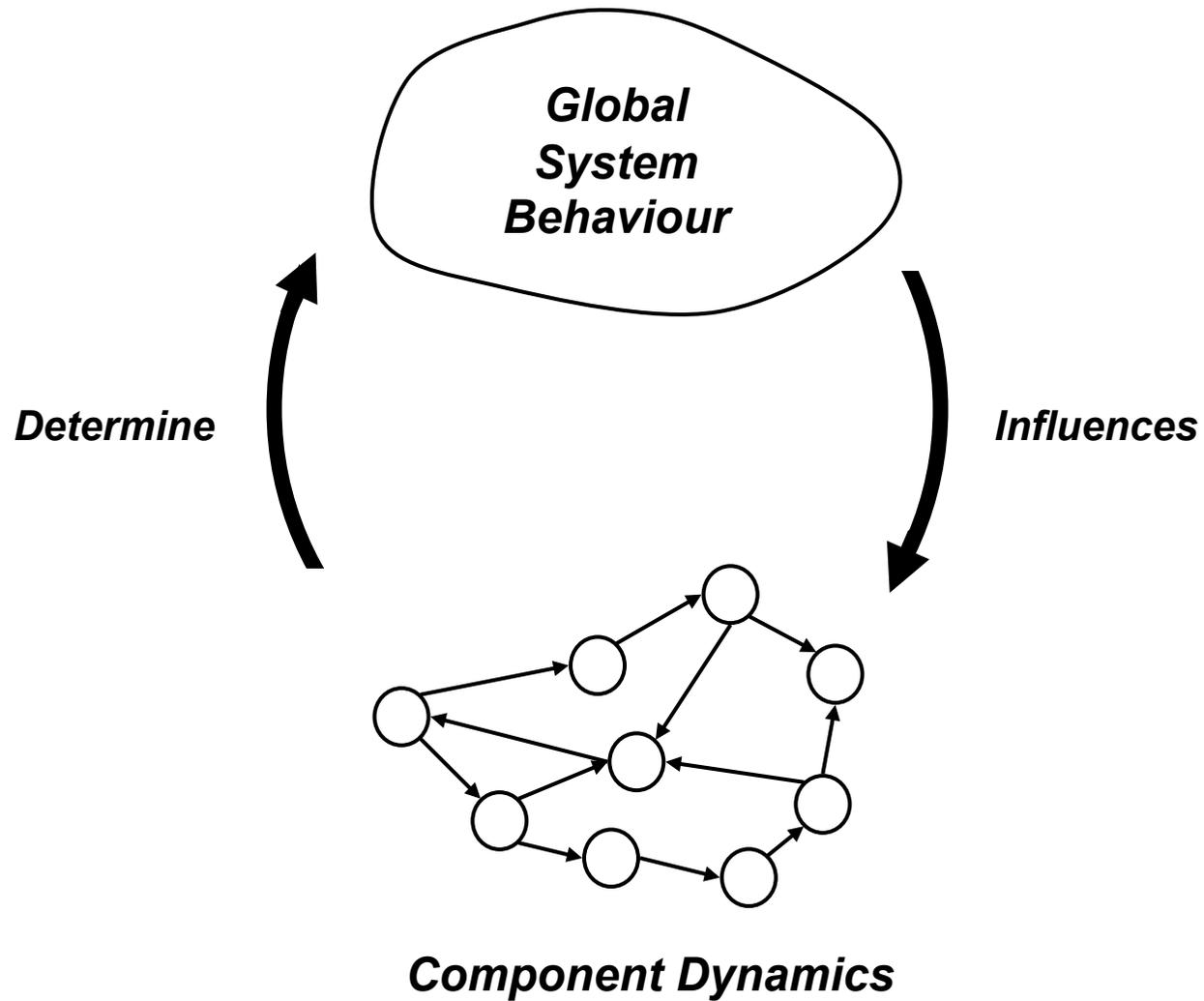
[Camazine 2006]

- *Non-linearity in component interaction*
- *Mutual interaction of local and global*

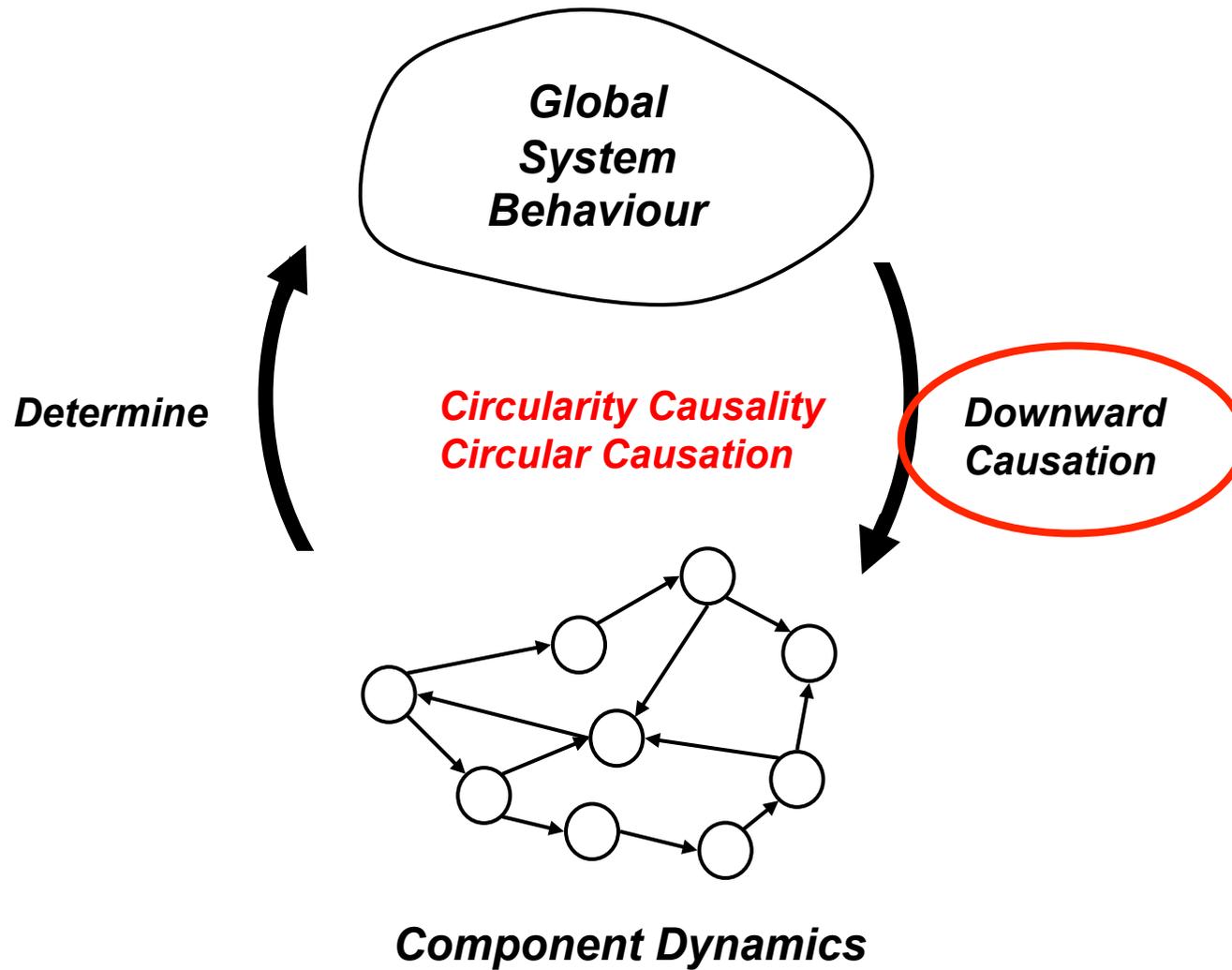
Continuous Reciprocal Causation (CRC)



Continuous Reciprocal Causation (CRC)



Continuous Reciprocal Causation (CRC)



Take-home message:

Emergent self-organization is autonomous

and

Autonomous systems typically involve some form of emergent self-organization

Autonomic Systems

Autonomic Systems

Systems that can manage themselves, given high-level objectives from administrator

Inspired by the autonomic nervous system

Operates automatically to regulate the body's physiological functions such as heart-beat, breathing, and digestion

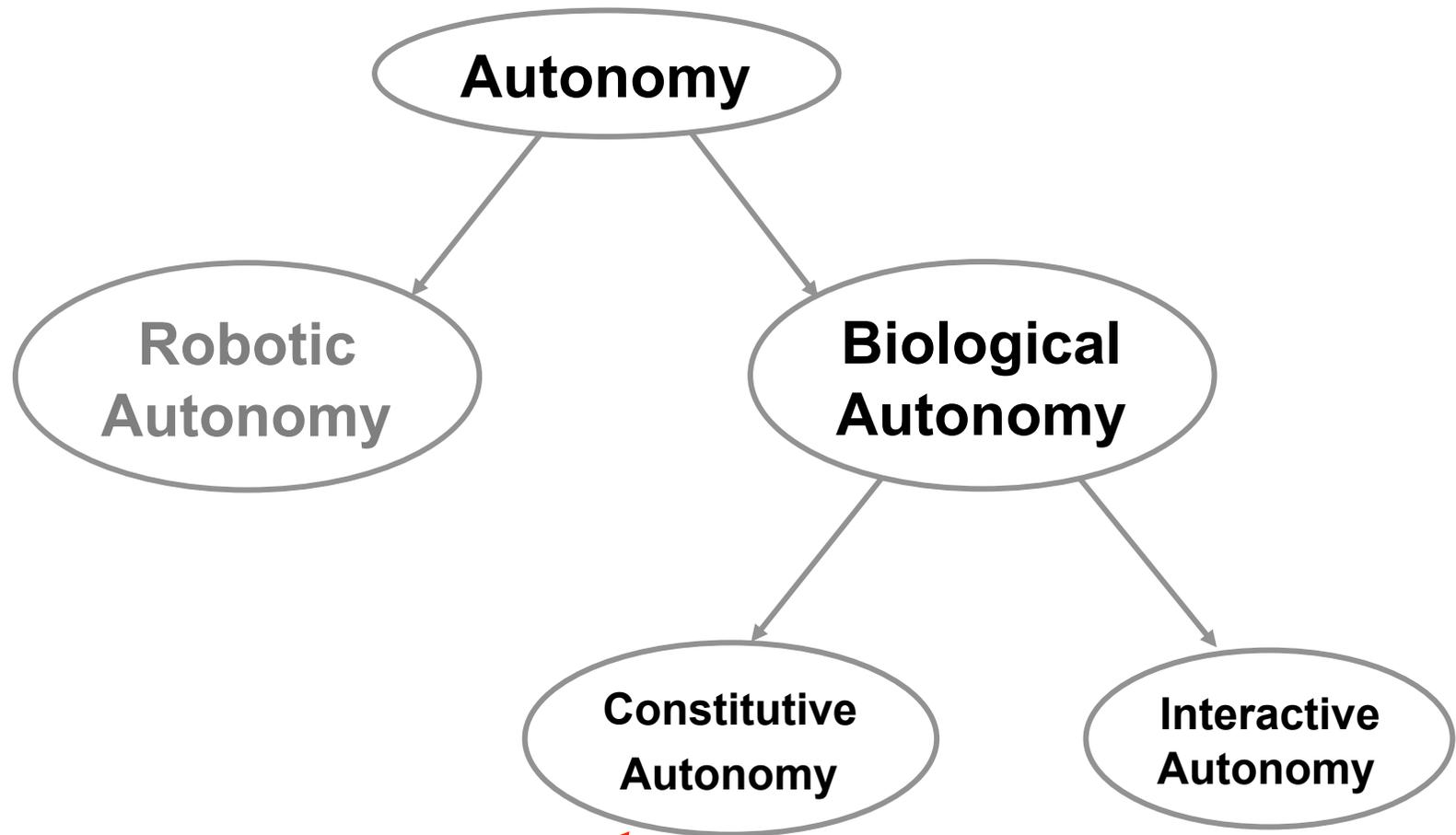
Closely related to homeostasis

Self-configuring

Self-healing

Self-optimizing

Self-protecting



Autonomic Processes

Scales of Autonomy

Different Scales of Autonomy

Autonomy appears at different levels in hierarchies in natural systems

- Ant colony and an individual ant
- An eco-system, e.g. a tidal lake, and the constituent species of flora and fauna

*Degree of autonomy depends on perspective:
viewed from which level of the hierarchy*

Autonomy & Goals

Autonomy and Goals

Autonomous systems set their own goals

How do you get it to do something useful for others?

Adjustable, shared, sliding, and subservient autonomy

Trade-off between autonomy and needs of other agents

Autonomy and Goals

“This is the apparent paradox of autonomy. The system should in some sense build itself, the designer should intervene less, but it should at the same time be more intelligently involved in setting the right processes in motion”

[Di Paolo and Iizuka 2008]

Measuring Autonomy

Measuring Autonomy

Formal mathematical theory of autonomous systems?

Good place to start: measuring autonomy

Causal autonomy

The degree to which Mutual Information between the system and its environment is caused by the environment or by the system itself

[N. Bertschinger, E. Olbrich, N. Ay, and J. Jost. Autonomy: An information theoretic perspective. Biosystems, 91(2):331–345, 2008.]

Measuring Autonomy

Formal mathematical theory of autonomous systems?

Good place to start: measuring autonomy

G-autonomy

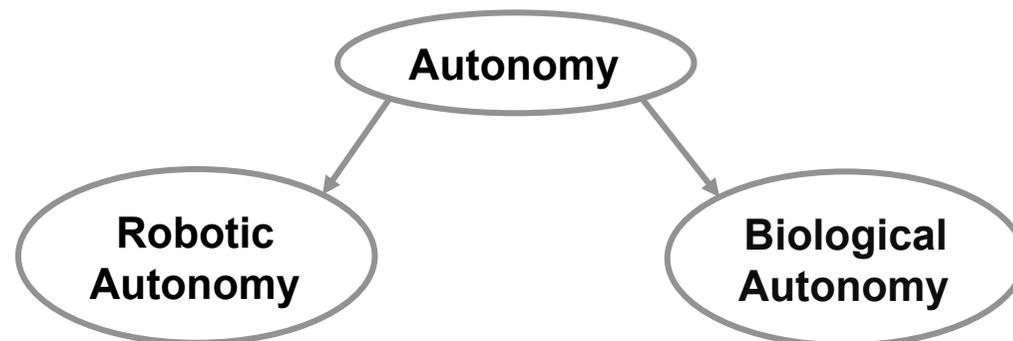
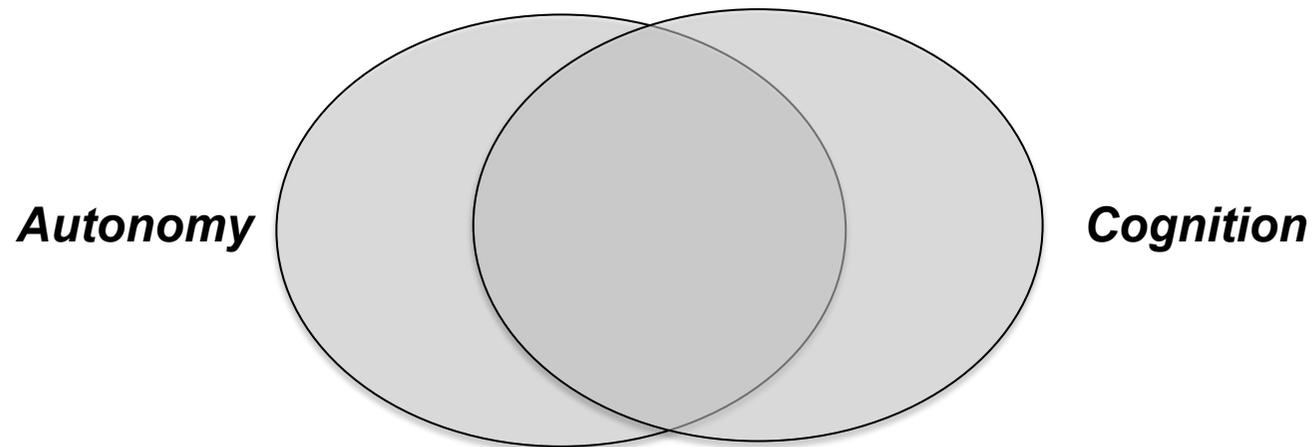
“... prediction of .. future evolution is enhanced by considering its own past states, as compared to predictions based on past states of a set of external variables”

Based on Granger Causality

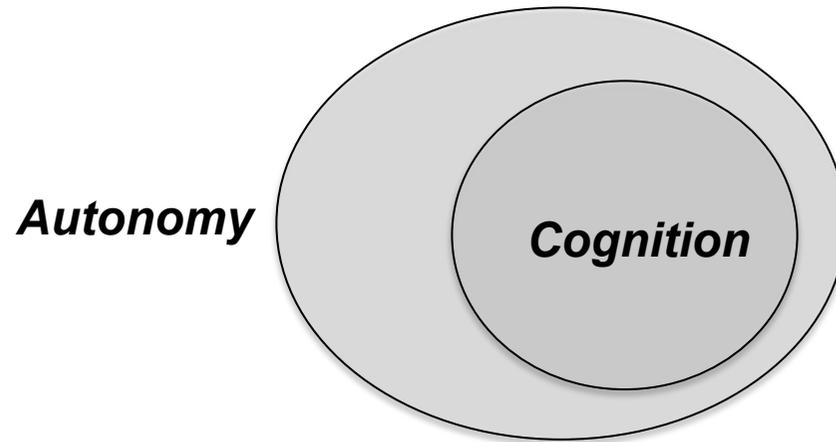
[A. Seth. Measuring autonomy and emergence via Granger causality. Artificial Life, 16(2):179–196, 2010.]

Autonomy & Cognition

*Is autonomy an important characteristic of cognition?
Is cognition an important characteristic of autonomy?*

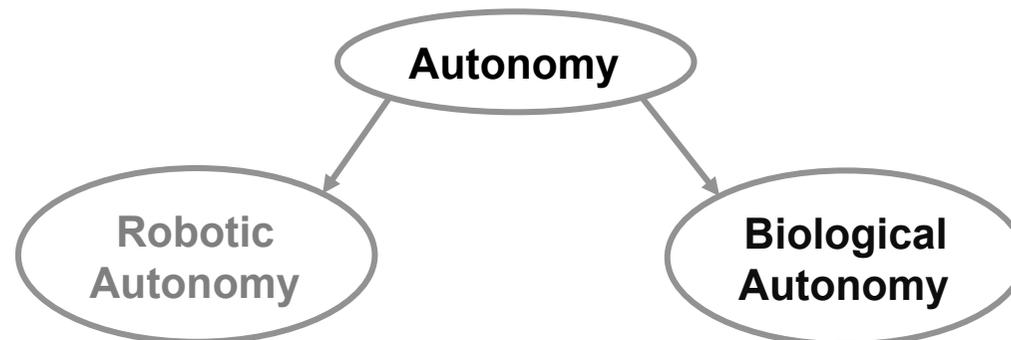


*Is autonomy an important characteristic of cognition?
Is cognition an important characteristic of autonomy?*



“The grounds of cognition are adaptive far-from-equilibrium autonomy — recursively self-maintenant autonomy”

[Bickhard 2000]



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Historical embodiment
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Embodiment



Embodied cognition
Situated cognition
Embedded cognition
Grounded cognition
Extended cognition
Distributed cognition

Anderson 2003; Shapiro 2007; Shapiro 2011	Embodied cognition
Clancey 1997; Robbins and Aydede 2008	Situated cognition
Wilson and Foglia 2012	Embedded cognition
Barsalou 2008; Barsalou 2010	Grounded cognition
Clark and Chalmers 1998; Clark 2008; Fodor 2009	Extended cognition
Hutchins 1995; Hollan, Hutchins, Kirsh 2000	Distributed cognition

What role does a body play in cognition?

(Not everyone thinks it does play a role)

If it does, we refer to **embodied cognition**



Embodied cognition
Situated cognition
Embedded cognition
Grounded cognition
Extended cognition
Distributed cognition

M. L. Anderson. Embodied cognition: A field guide. *Artificial Intelligence*, 149(1):91–130, 2003.

P. Calvo and T. Gomila, editors. *Handbook of Cognitive Science: An Embodied Approach*. Elsevier, 2008.

R. Chrisley and T. Ziemke. Embodiment. In *Encyclopedia of Cognitive Science*, pages 1102–1108. Macmillan, 2002.

A. Clark. *Being There: Putting Brain, Body, and World Together Again*. MIT Press, Cambridge, MA, 1997.

L. Shapiro. *Embodied Cognition*. Routledge, 2011.

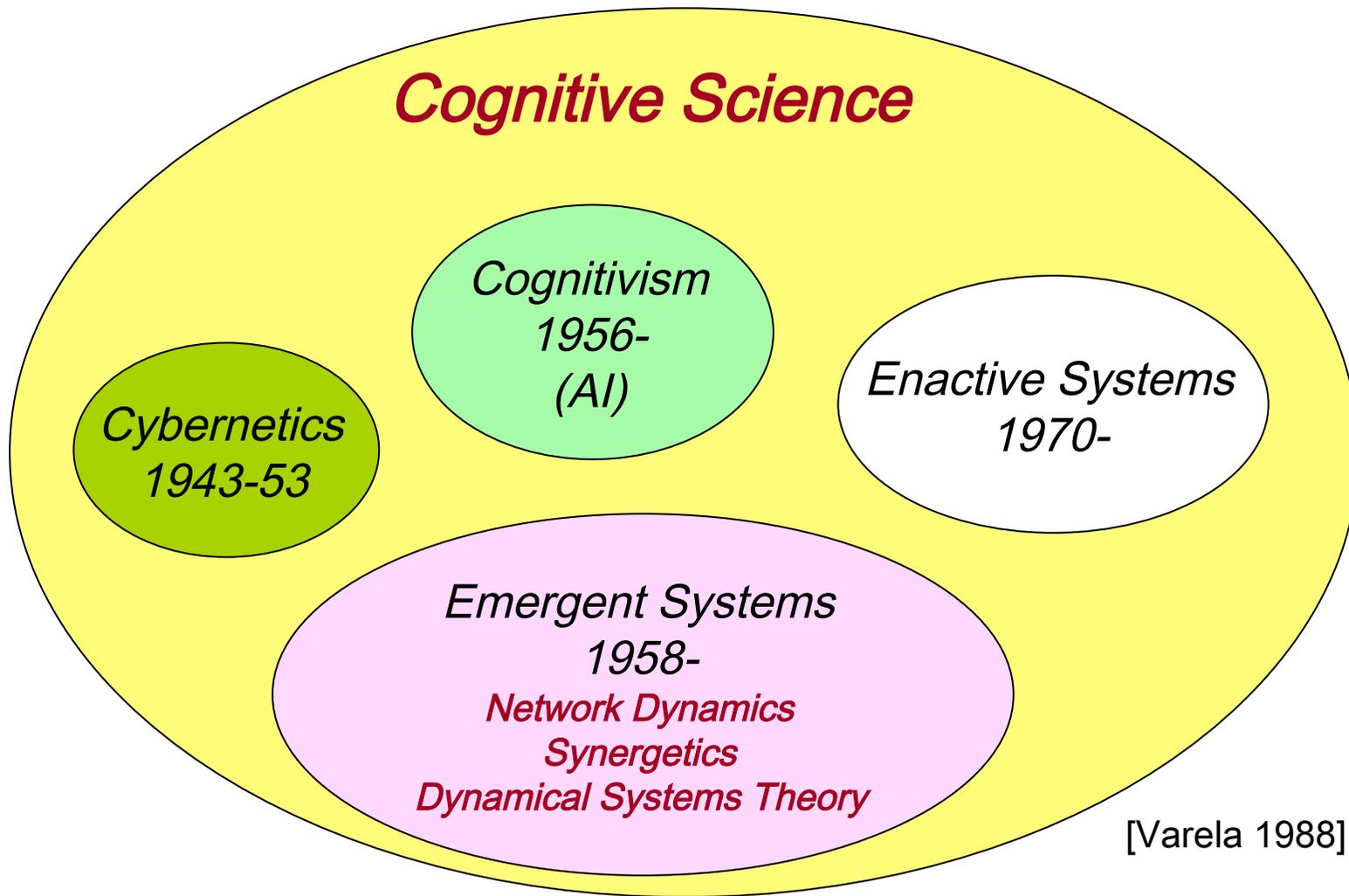
F. Varela, E. Thompson, and E. Rosch. *The Embodied Mind*. MIT Press, Cambridge, MA, 1991.

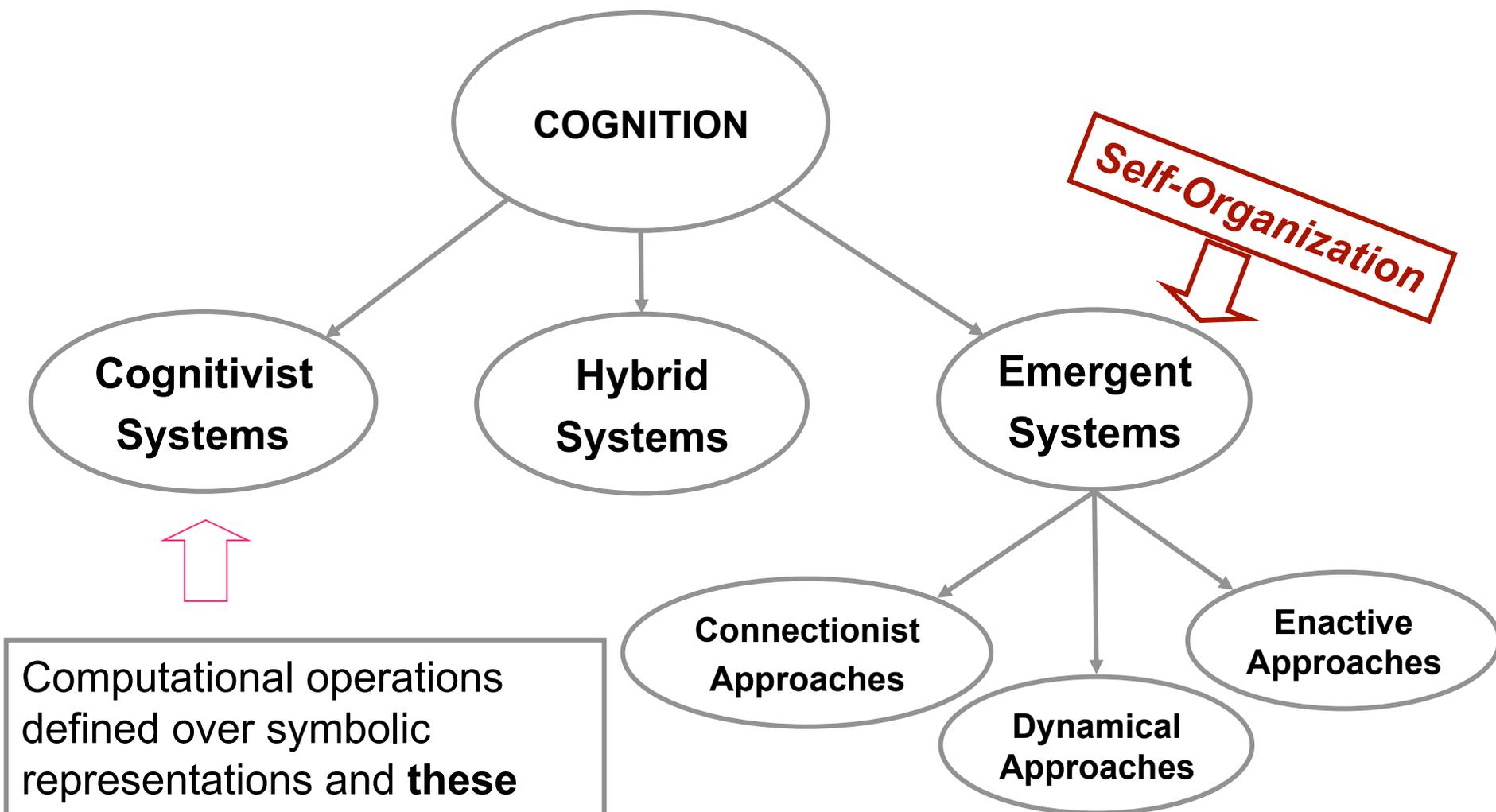
M. Wilson. Six views of embodied cognition. *Psychonomic Bulletin & Review*, 9(4):625–636, 2002.

T. Ziemke. Introduction to the special issue on situated and embodied cognition. *Cognitive Systems Research*, 3(3):271–274, 2002.

euCognition. euCognition tutorial on embodiment. <http://www.eucognition.org/index.php?page=tutorial-on-embodiment>, 2013.

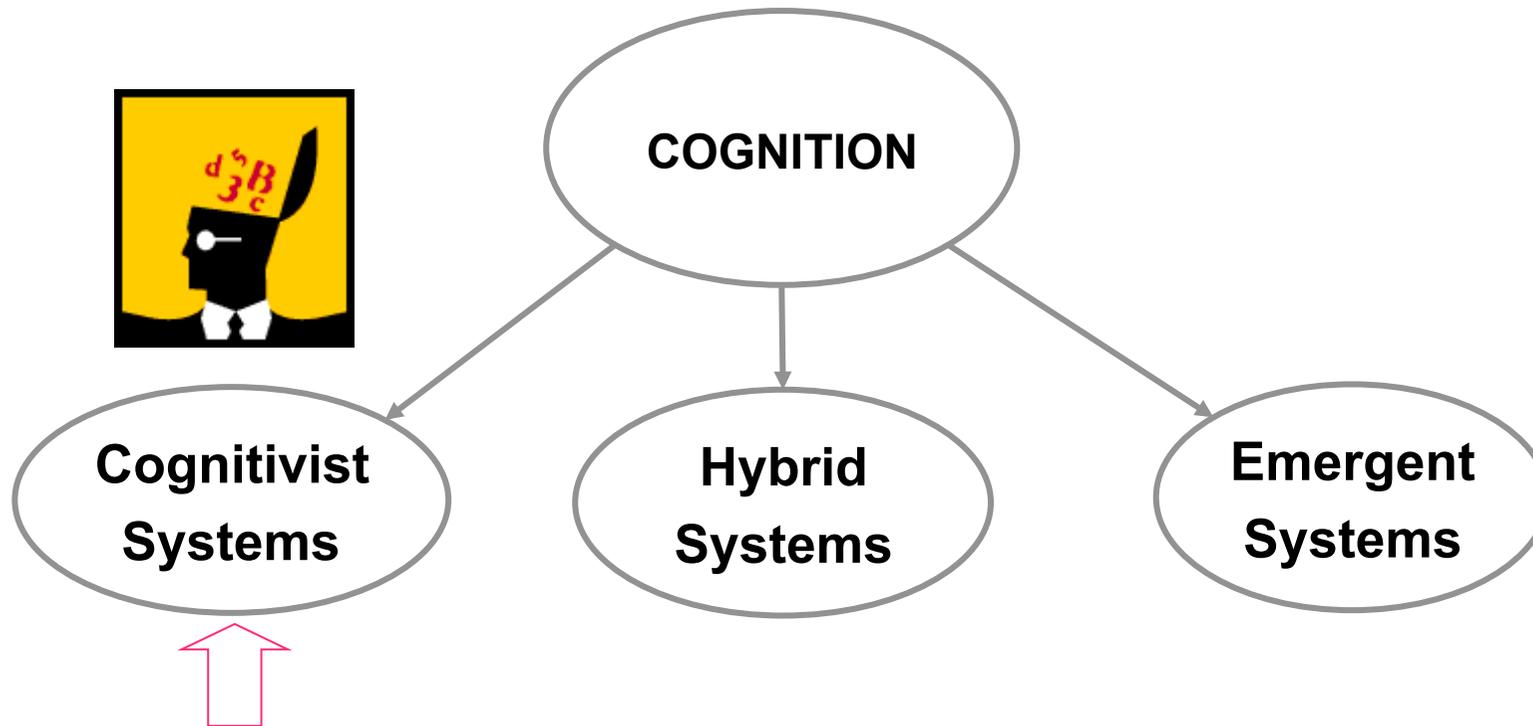
Cognitive and Emergent Perspectives on Embodiment





Computational operations defined over symbolic representations and **these operations are not tied to any given instantiation**

[Vernon, Metta, Sandini 2007]

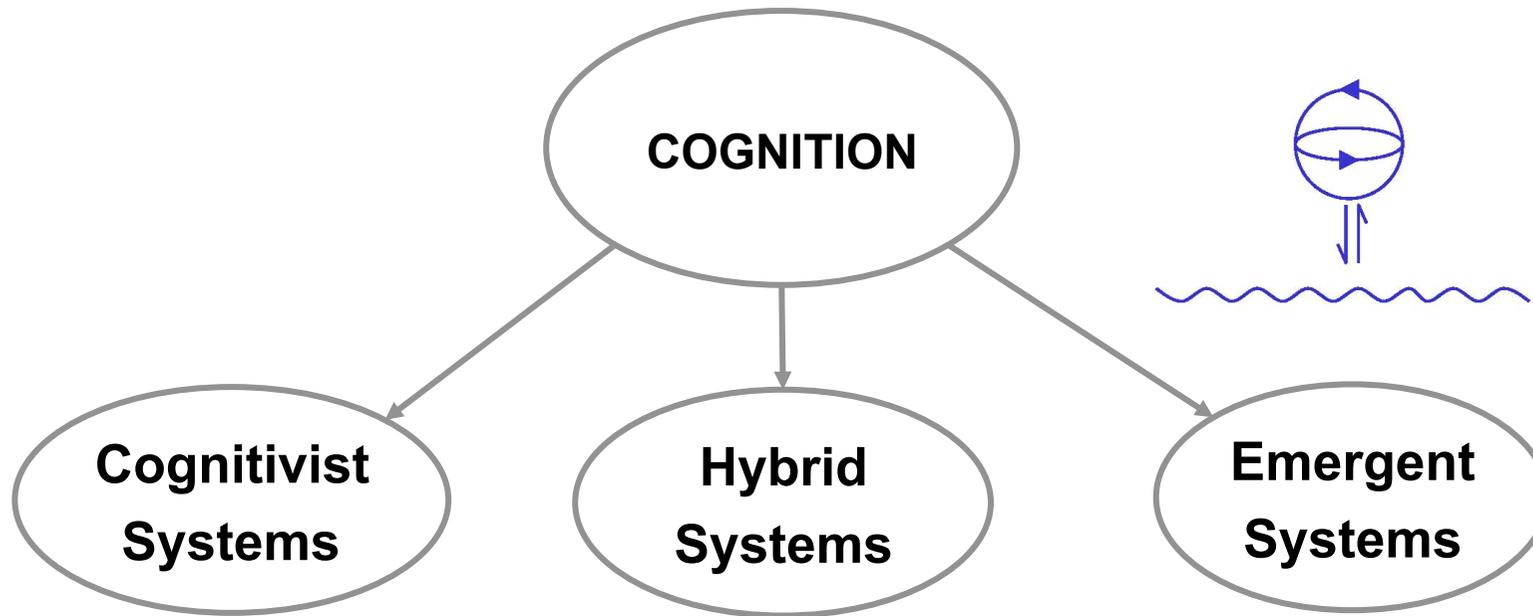


There is no need for embodiment

Physical symbol system hypothesis – **computational functionalism**

Symbolic knowledge can be programmed in directly

Embodiment may be useful, but it's not necessary

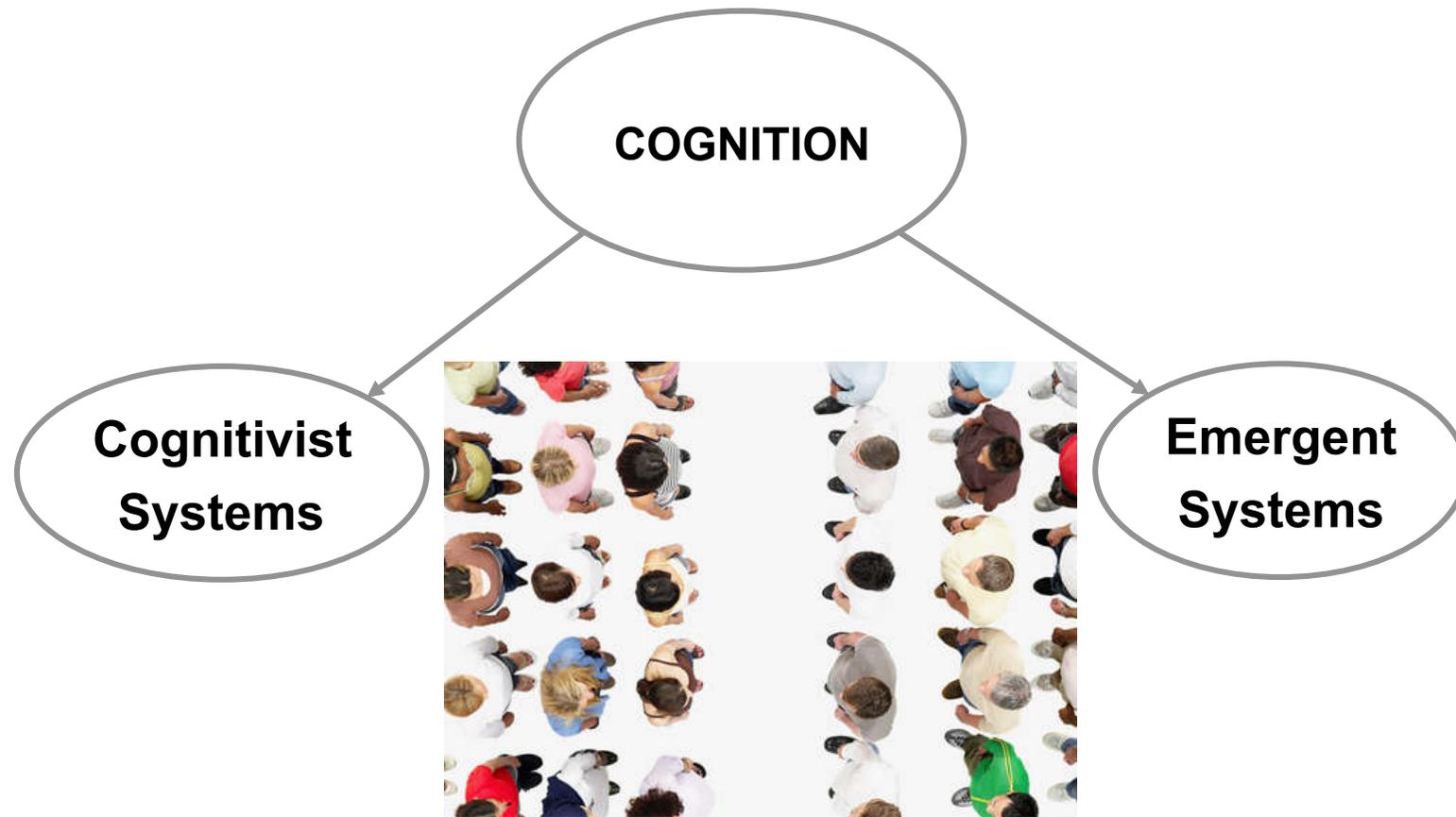


Must be embodied

Developing through real-time interaction with the environment

Self-organization

Structural coupling with the environment



The Embodied Cognition Thesis

Basic Assumption of Embodied Cognition

The cognitive agent exists in some ecological niche and that the **brain-body** system has evolved to take advantage of the particularities of its environment

Embodied Cognition Thesis

“Many features of cognition are embodied in that they are deeply dependent upon characteristics of the physical body of an agent, such that **the agent’s beyond-the-brain body plays a significant causal role**, or physically constitutive role, in that agent’s cognitive processing.”

R. A. Wilson and L. Foglia. Embodied cognition. In E. N. Zalta, editor, The Stanford Encyclopedia of Philosophy. 2011.

Embodied Cognition Thesis

Embodiment:

1. Physiology
2. Evolutionary history
3. Practical activity
4. Its socio-cultural situation

Embodied Cognition Thesis

Embodiment:

1. Physiology
2. Evolutionary history
3. Practical activity
4. Its socio-cultural situation

Rough/smooth
depends on tactile
sensors

Steep hill depends
on physiology &
training

Agents with different
type of bodies
understand the
world differently

Embodied Cognition Thesis

Embodiment:

1. Physiology
2. Evolutionary history
3. Practical activity
4. Its socio-cultural situation

Often we recruit older (in evolutionary terms) cognitive capabilities in new ways

Carrying these mechanisms forward from generation to generation is the agent's embodiment, encoded in its genes

Embodied Cognition Thesis

Embodiment:

1. Physiology
2. Evolutionary history
3. Practical activity
4. Its socio-cultural situation

Solving problems very often relies on physical trial and error

Dependent on your physical capabilities

You develop an understanding of the environment in terms of your embodied action capabilities

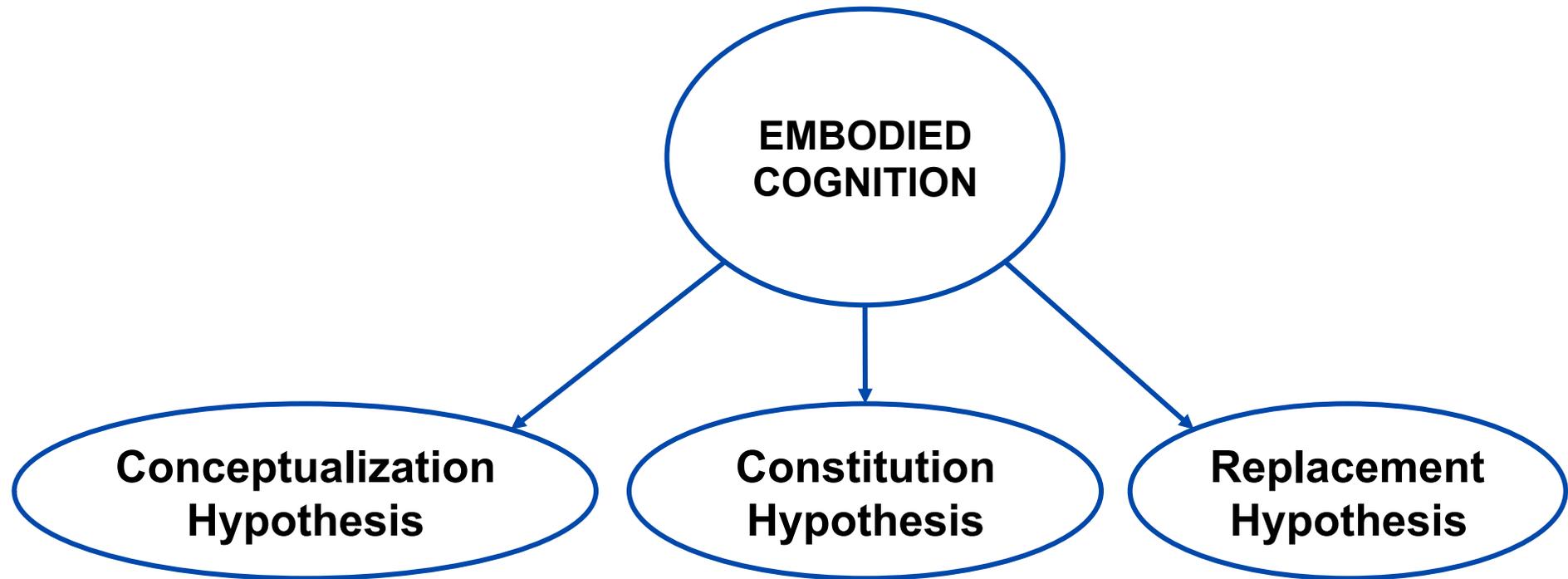
Embodied Cognition Thesis

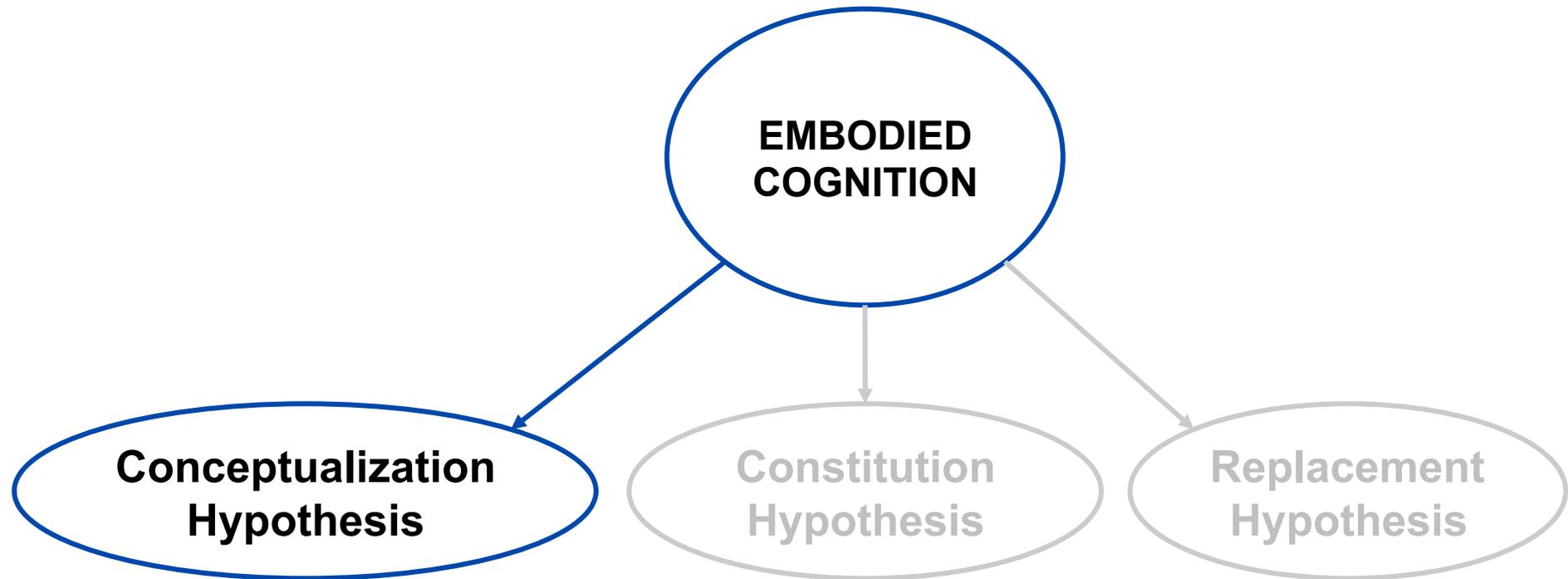
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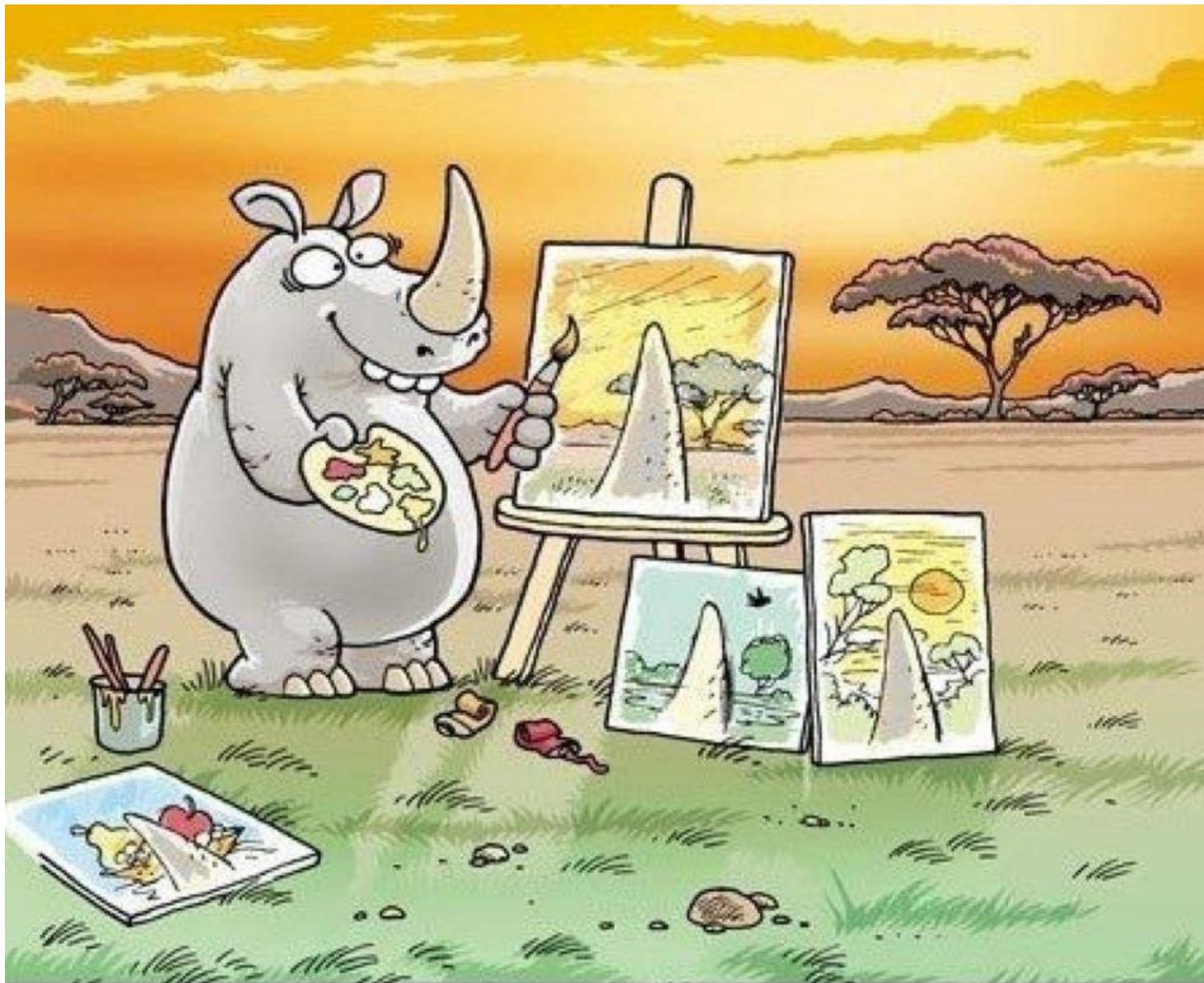
Hand gestures, for example, can have completely different meanings in different cultures

Three Hypotheses on Embodied Cognition

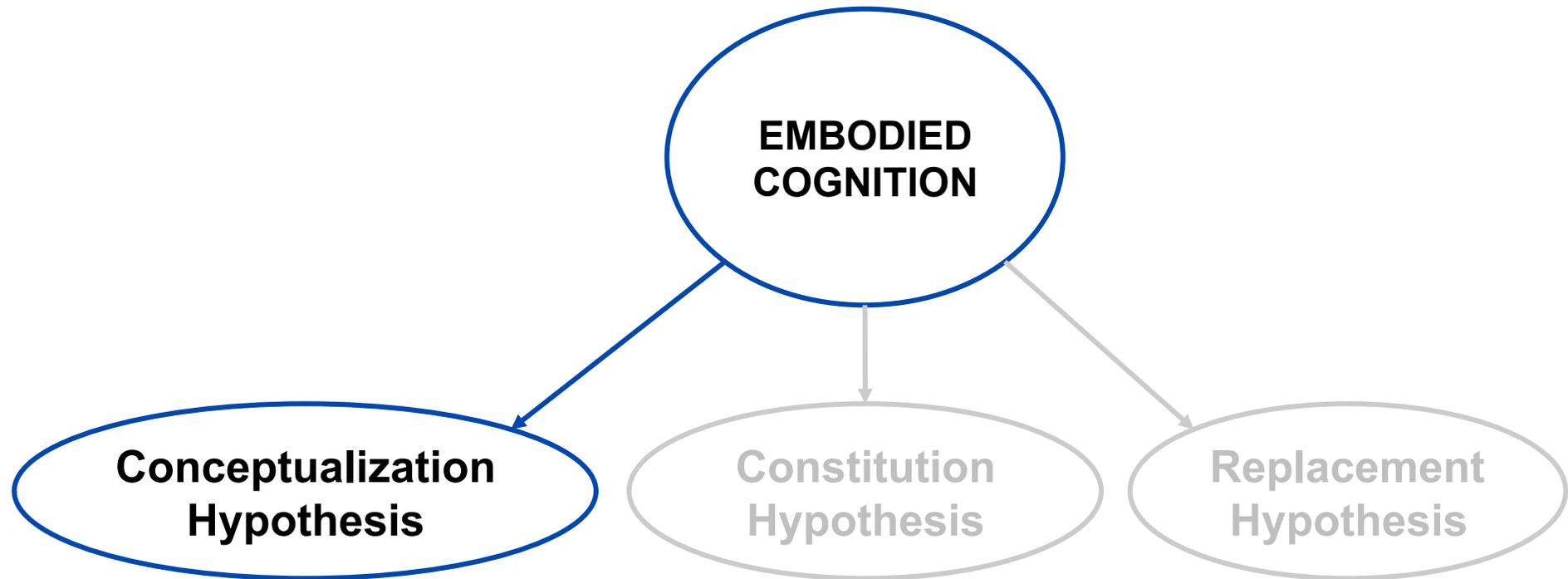




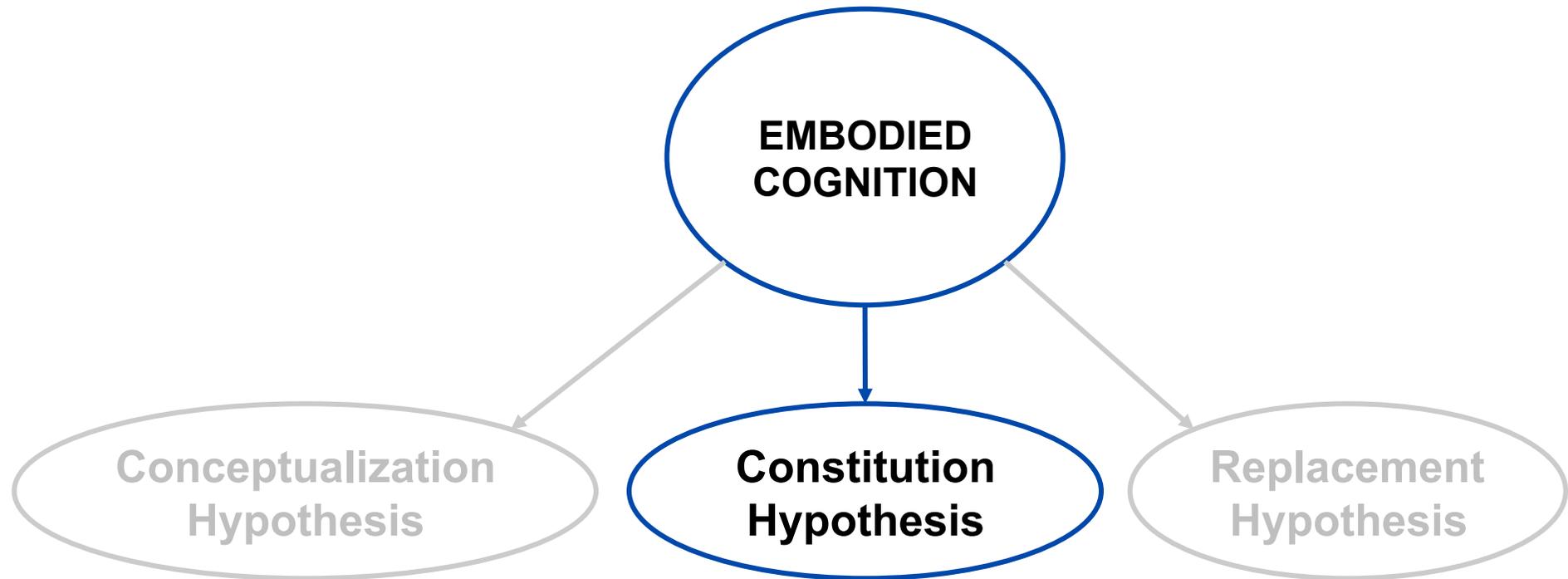
The characteristics of an agent's body determine the concepts an organism can acquire



**You see the world
as you are!**

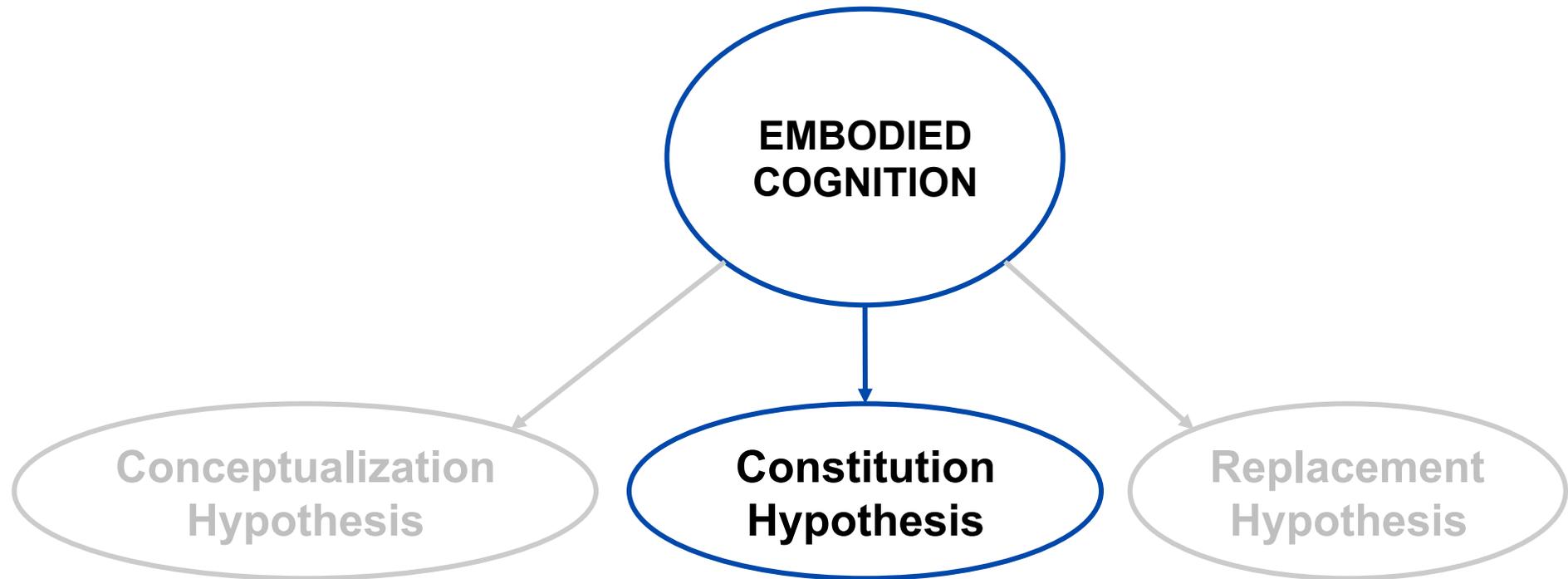


The body conditions / constrains cognition

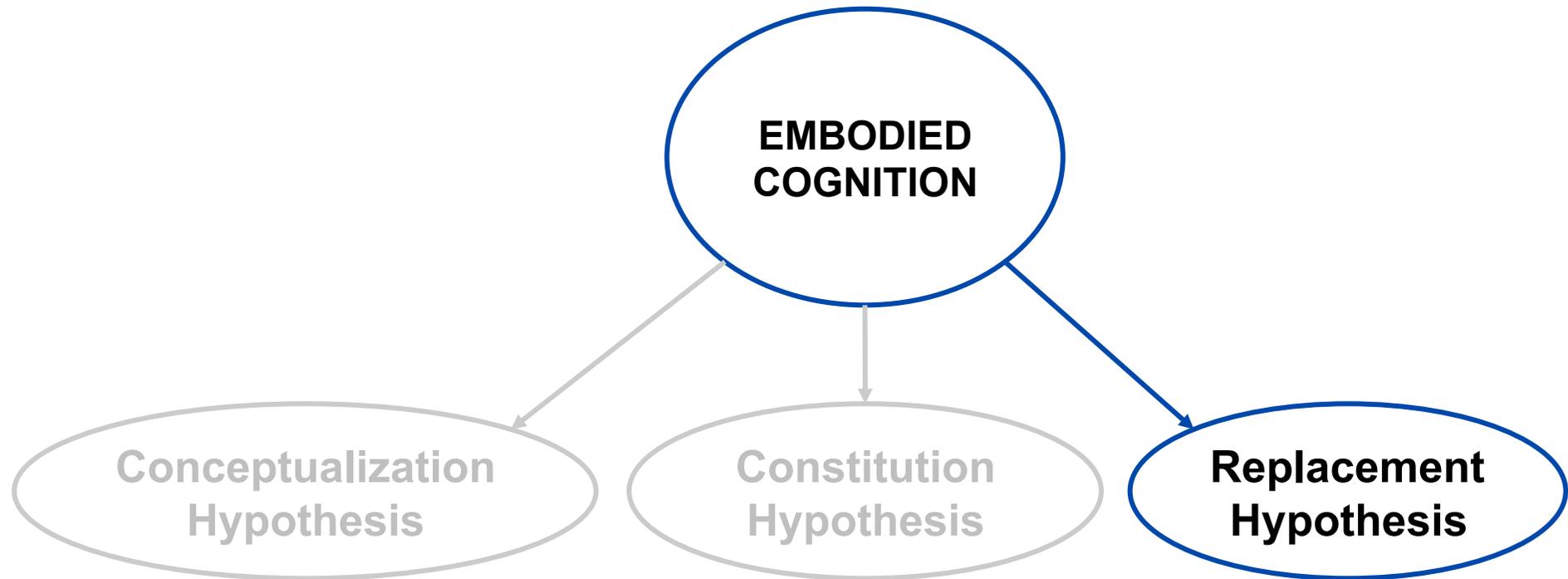


The body is itself an integral part of cognition

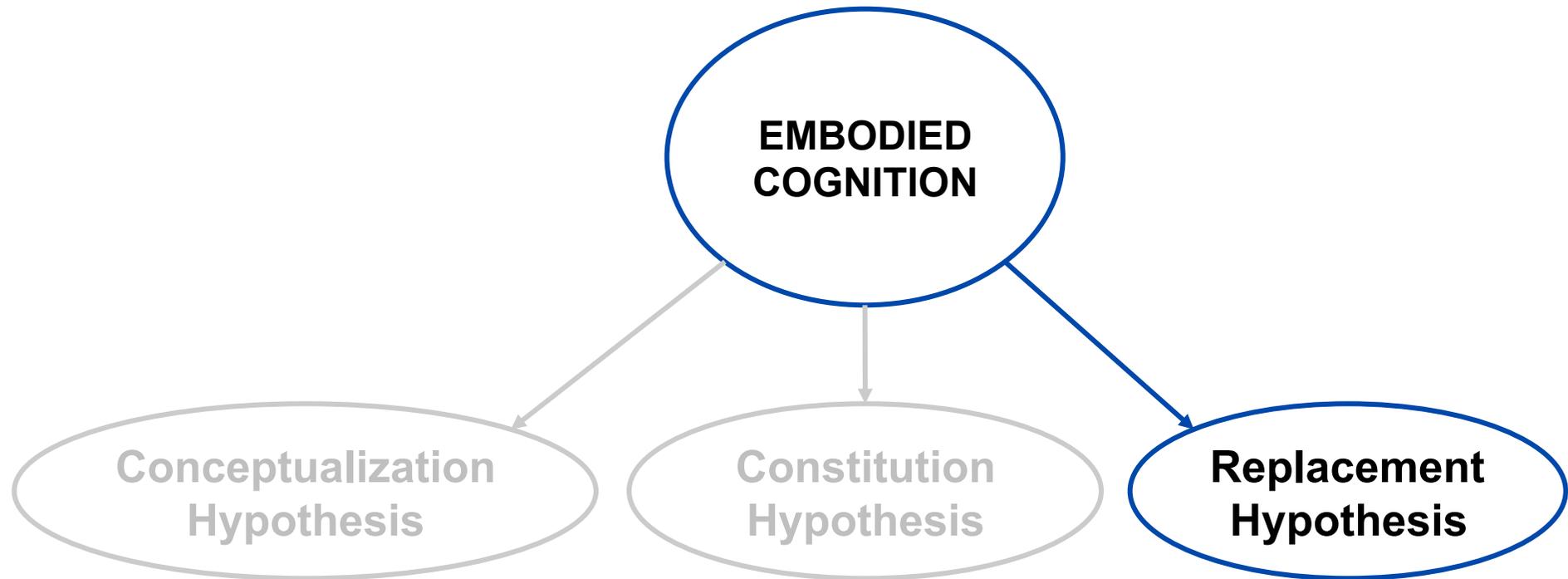
The way the body is shaped and moves **augments** brain-centred neural processing



The body simplifies what the brain has to do or takes over responsibility for it completely



An agent's body in real-time interaction with its environment **replaces** the need for representational processes
(with dynamical systems based perception-action couplings)



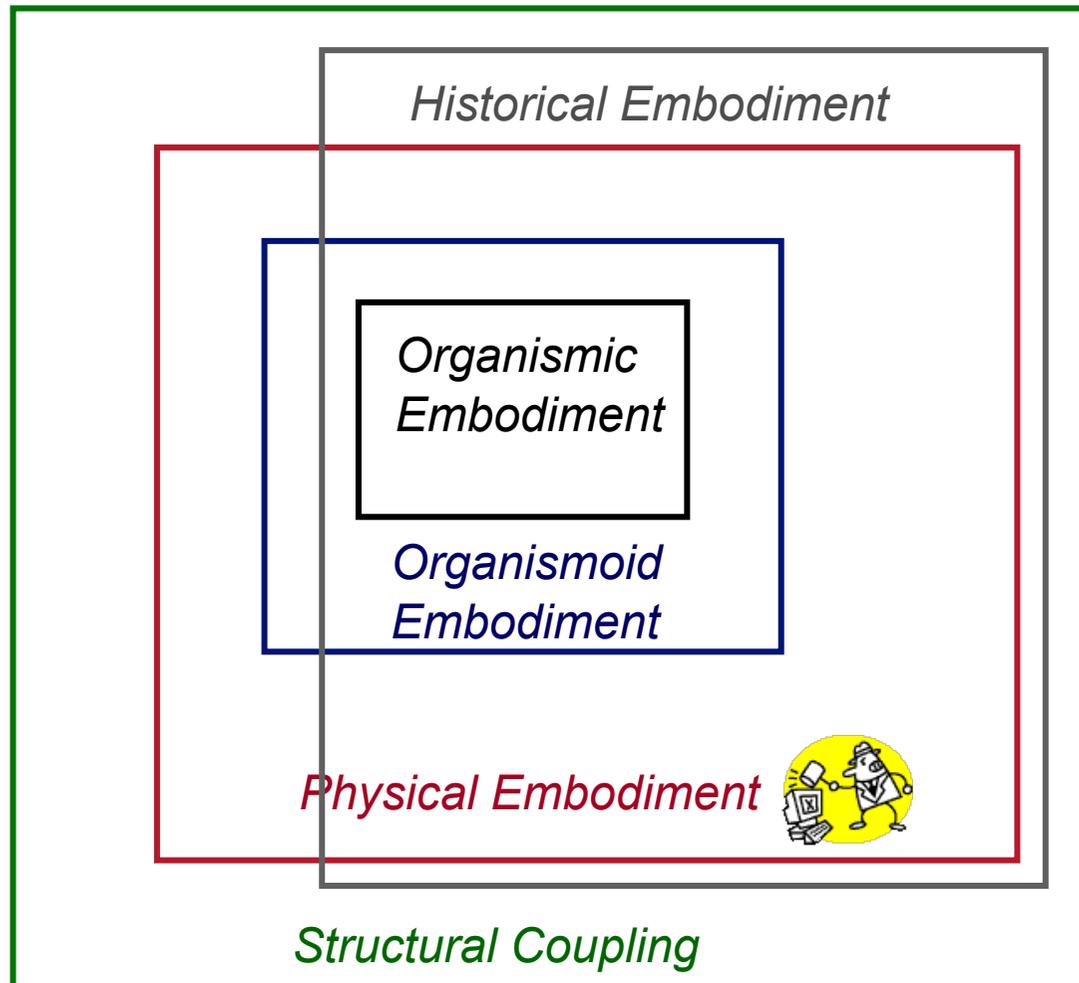
The body acts as a regulator of cognitive activity

Evidence for the Embodied Stance

Evidence for the Embodied Stance: the Mutual Dependence of Perception and Action

- Spatial and selective attention
- The Pinocchio effect
- Canonical and mirror visuo-motor neurons in F5
- Affordances

Types of Embodiment



From: T. Ziemke, 'What's this thing called embodiment?', 2003

Types of Embodiment

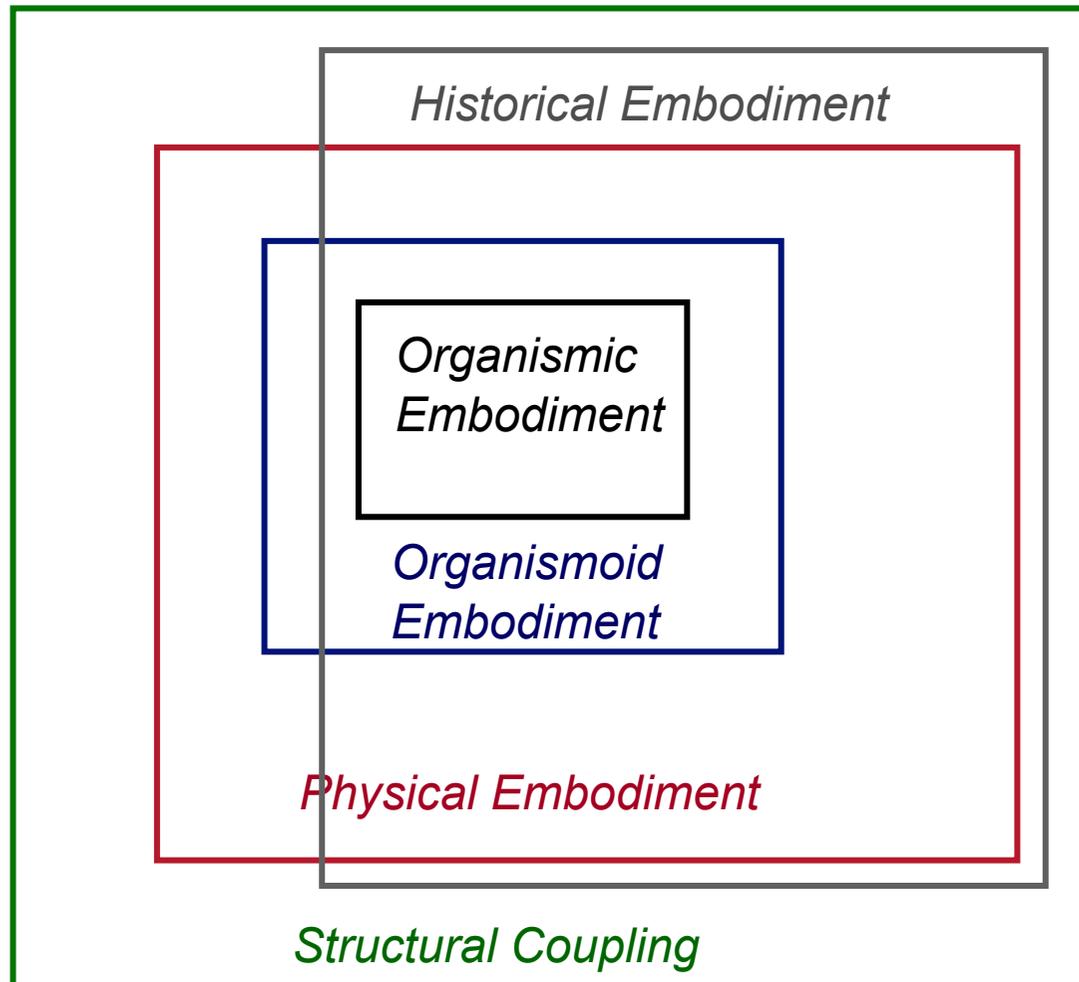
Social embodiment:

The mutual relationship between body states and cognitive and affective (i.e. emotional) states in social interaction

1.

2.

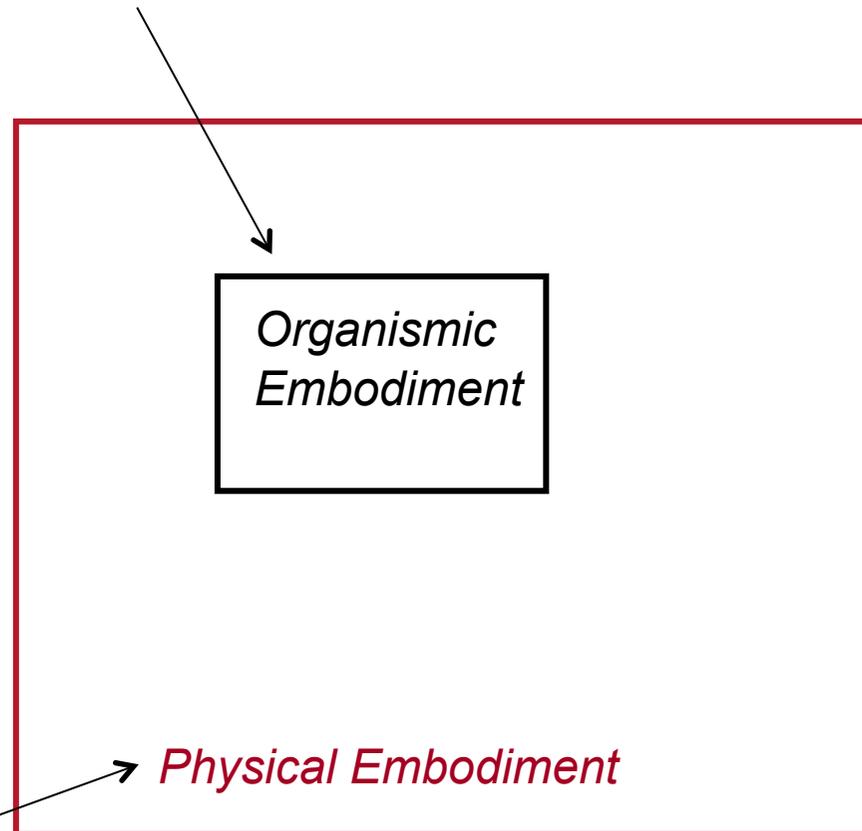
3. Agent's own bodily states, such as posture, constitute a powerful trigger for affective states in the agent



From: T. Ziemke, 'What's this thing called embodiment?', 2003

Phenomenal Embodiment

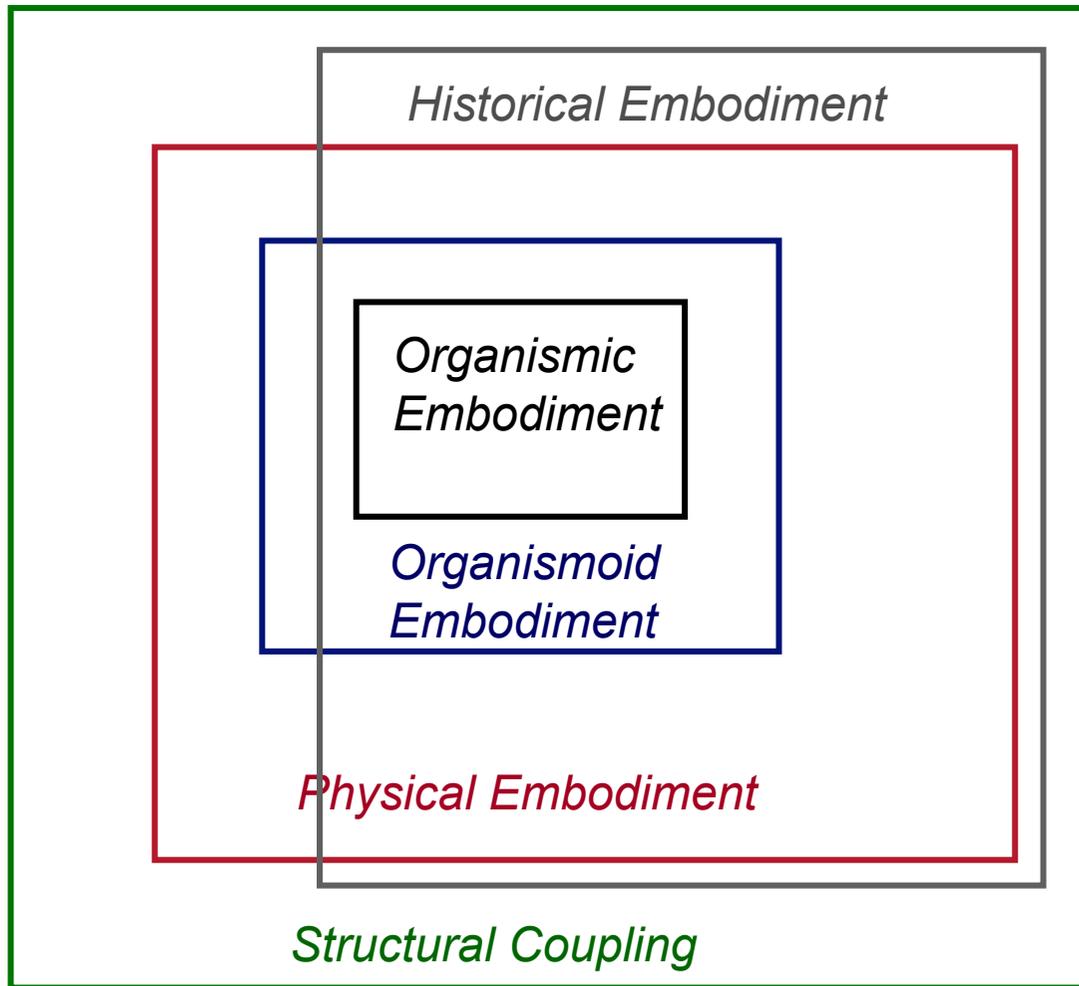
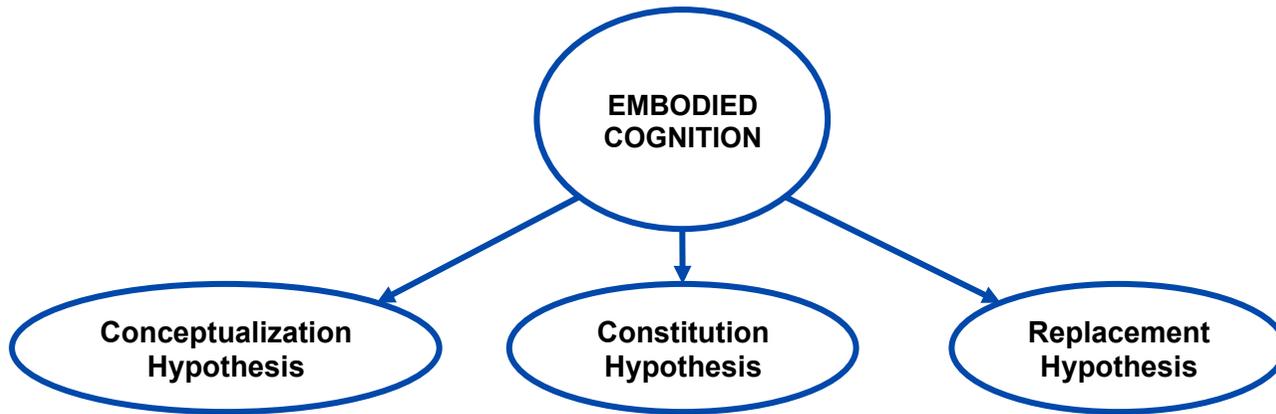
Embodied cognition is uniquely reserved to living entities that exist in some environmental niche and have a subjective experience of that environment

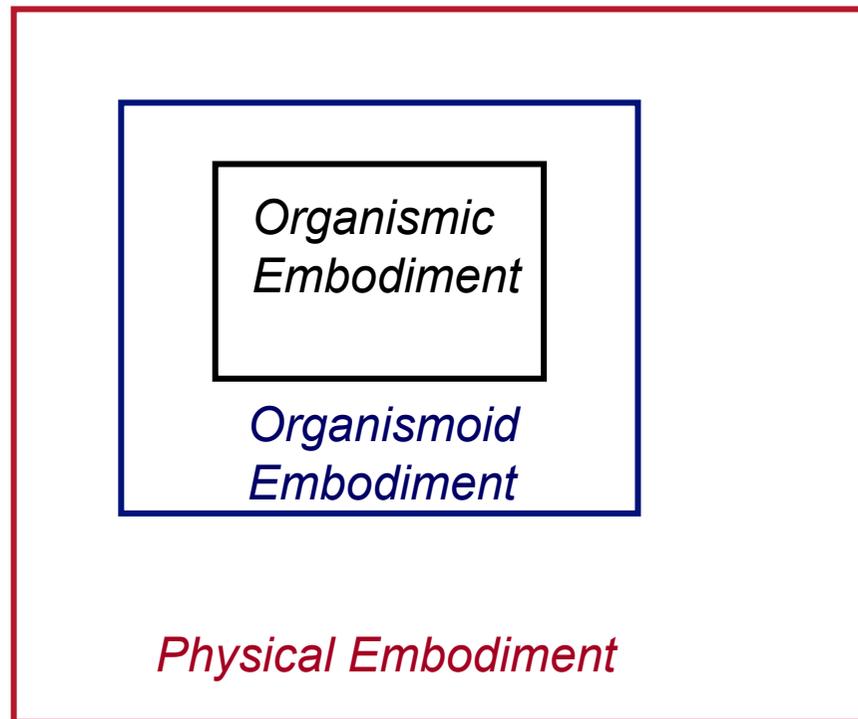
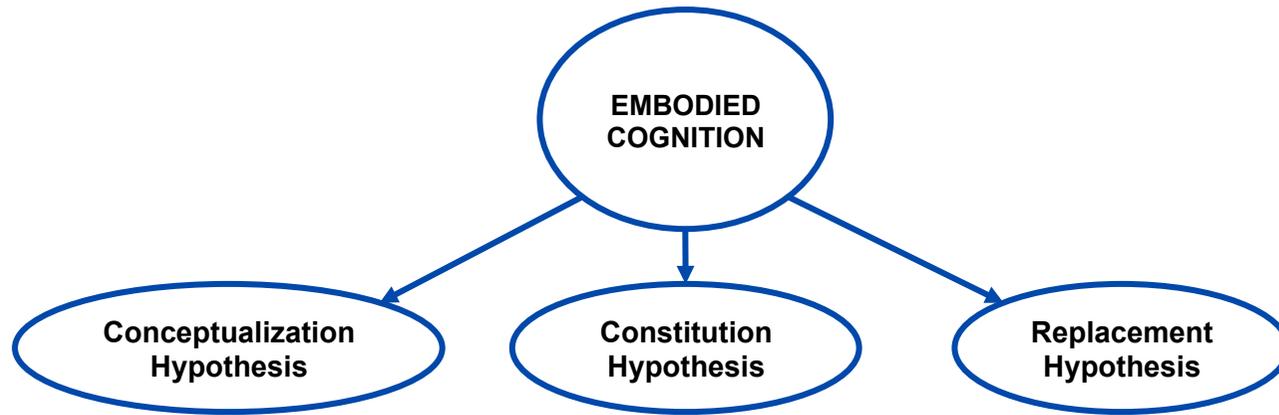


Mechanistic Embodiment:

Everything you need for cognitive activity is there in the physical mechanism

(cf. Replacement Hypothesis)





Inward-looking Aspects of Embodiment

Inward-looking Aspects of Embodiment

1. Off-line Embodied Cognition (Internal Simulation)
2. Internal Interaction

Off-line Embodied Cognition

- Cognition is primarily concerned with action
- And with preparing for action:
offline cognition / internal simulation
- Multiple options for action
- Choosing on the basis of internal attention
- Based on flow of perceptions

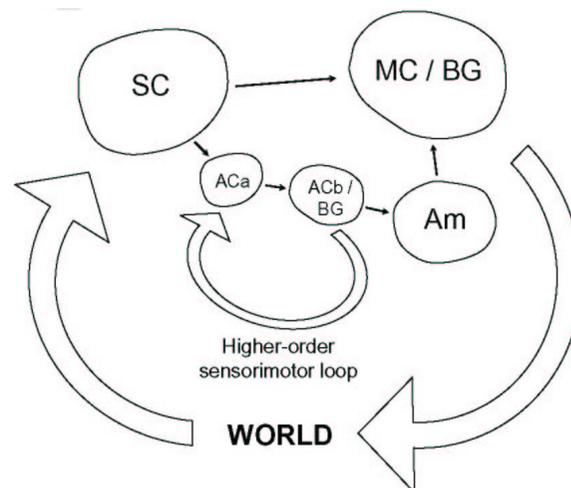
Off-line Embodied Cognition

- Cognitive system as a whole is the simulator
- HAMMER architecture
 - Multiple inverse models
 - Input current state and goals, output motor commands
 - Multiple forward models
 - Input motor commands, output predicted outcome

Y. Demiris and B. Khadhour. Hierarchical attentive multiple models for execution and recognition (HAMMER). Robotics and Autonomous Systems, 54:361–369, 2006.

Off-line Embodied Cognition

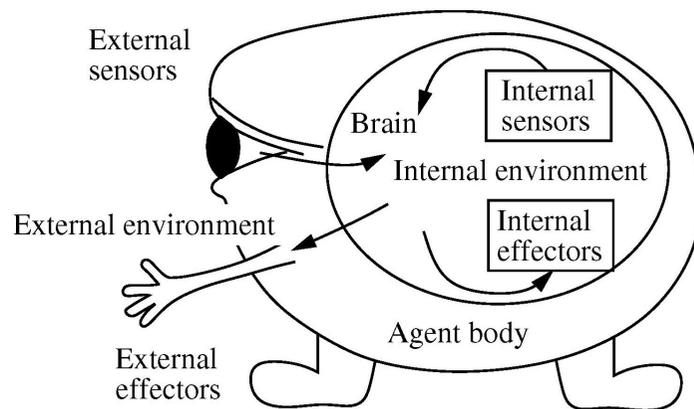
- ***Off-line cognition is still body-based*** ←
- The cognitive activity is still grounded in the mechanisms of sensory processing and motor control



[Shanahan06, ShanahanBaars06, Shanahan05a, Shanahan05b]

Internal Interaction

- Interaction between the agent and its own internal body
- Interaction with the CNS:

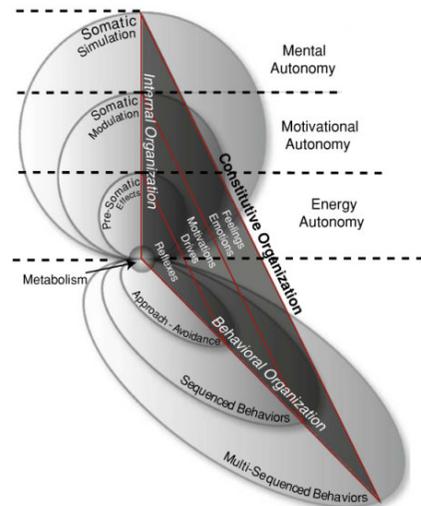


Self-aware self-effecting (SASE) agent

[Weng et al. 01, Weng 02, Weng & Zhang 02, Weng 04a, Weng 04b]

Internal Interaction

- Interaction between the agent and its own internal body
- Interaction with the affective system & metabolism



The Cognitive-Affective Architecture Schematic

A. Morse, R. Lowe, and T. Ziemke. 2008.

Internal Interaction

- Cognition >> memory, attention, and reasoning
- Cognition >> co-dependence of action and perception
- Cognition: internal constitution of the embodied agent
 - Homeostatic processes
 - Affective processes that provide the **internal value systems which influence the goals of autonomous cognitive agents**

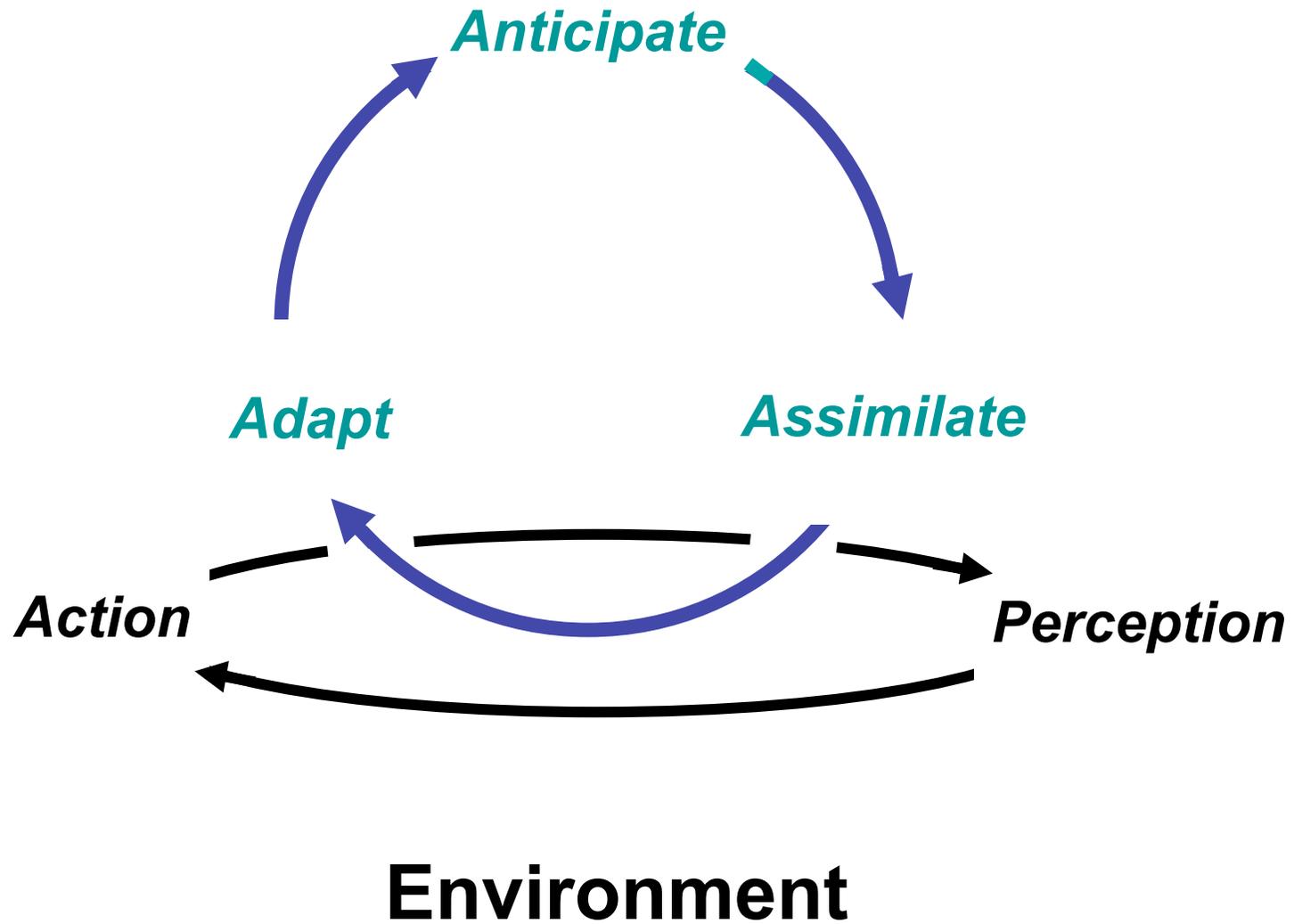
Internal Interaction

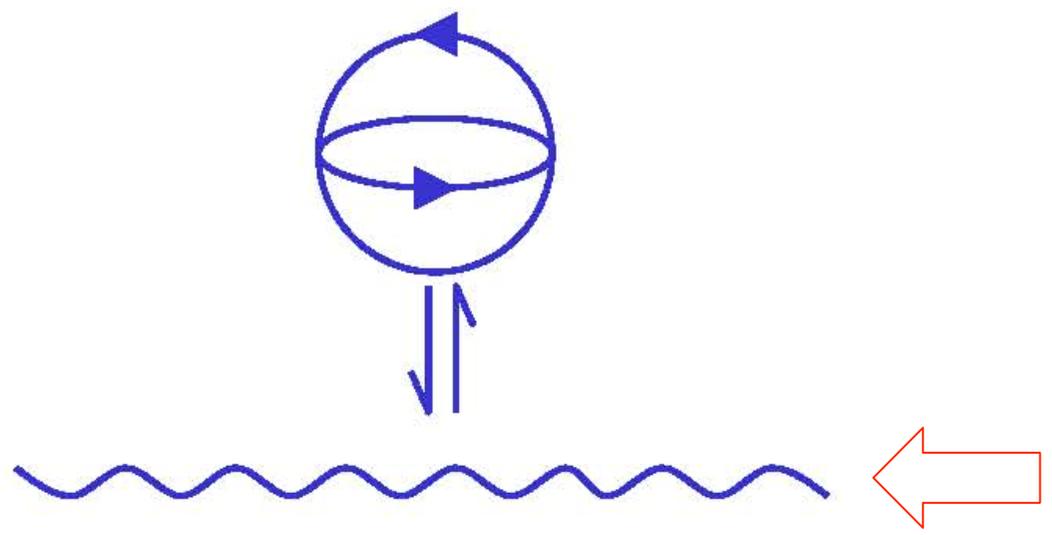
- Interoception & Internal Robotics [Parisi 2004]
 - CNS
 - Endocrinal System
- Being “properly embodied” [Mog Stapleton 2013]

D. Parisi. Internal Robotics. Connection Science, 16(4):325– 338, 2004.

M. Stapleton. Steps to a “Properly Embodied” cognitive science. Cognitive Systems Research, 22—23:1–11, 2013.

Brain—Body—Environment
Characteristic of
Embodied Cognition





Basic Assumption of Embodied Cognition

The cognitive agent exists in some **ecological niche** and that the brain-body system has **evolved to take advantage** of the **particularities** of its environment

Two sources of confusion

1. The part played by the environment
2. Some versions of embodiment don't need a body!

Situated Cognition

Situated Cognition

On-going real-time interaction with its environment

Structurally-coupled to the environment

Maintain its autonomy despite the precarious circumstances

W. J. Clancey. Situated Cognition: On Human Knowledge and Computer Representations. Cambridge University Press, Cambridge MA, 1997.

Embedded Cognition

Embedded Cognition

Off-load cognitive work onto the environment

Using landmarks to help remember your way home

Modify the environment

(External) Scaffolding

Create signs to help with navigation

R. A. Wilson and L. Foglia. Embodied cognition. In E. N. Zalta, editor, The Stanford Encyclopedia of Philosophy. 2011.

Grounded Cognition

Grounded Cognition

Less concerned with embodiment,
More concerned with the nature of representations

Modal (not amodal) representation

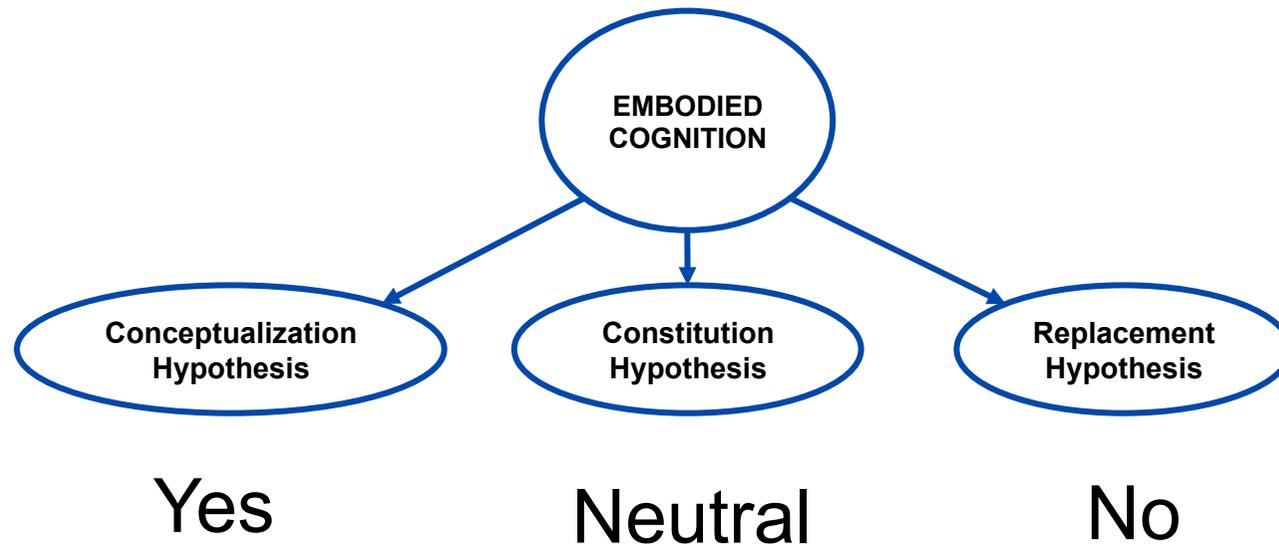
Symbolic but grounded in sensorimotor experience

Internal simulation is key, and is modal
Operates off-line, independently of the body

L. W. Barsalou. Grounded cognition. Annu. Rev. Psychol., 59(11):11.1–11.29, 2008.

L. W. Barsalou. Grounded cognition: Past, present, and future. Topics in Cognitive Science, 2:716–724, 2010.

Grounded Cognition



L. W. Barsalou. Grounded cognition. Annu. Rev. Psychol., 59(11):II.1–II.29, 2008.

L. W. Barsalou. Grounded cognition: Past, present, and future. Topics in Cognitive Science, 2:716–724, 2010.

Grounded Cognition

Modal representations can be based on **introspective internal simulations**

Do not necessarily involve a faithful complete reconstruction of embodied experience

Allows for the inclusion of **abstract concepts that are not grounded** directly in specific sensorimotor experiences

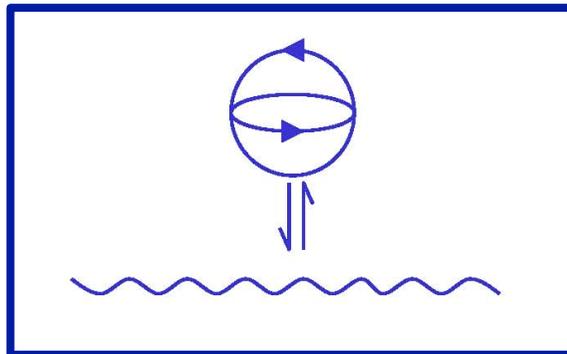
L. W. Barsalou. Grounded cognition. Annu. Rev. Psychol., 59(11):II.1–II.29, 2008.

L. W. Barsalou. Grounded cognition: Past, present, and future. Topics in Cognitive Science, 2:716–724, 2010.

Extended Cognition

Extended Cognition

The environment is a constitutive component in a bigger *brain-body-environment* cognitive system



A. Clark and D. Chalmers. The extended mind. Analysis, 58:10–23, 1998.

Extended Cognition

The environment is a constitutive component
in a bigger *brain-body-environment* cognitive system

Embodiment and body augmentation

Extendable body schema [Sato, Iizuka, Ikegami 2013]

“Bodies are not constant”

“The interaction defines the body”

Florentin Wörgötter

Distributed Cognition

Distributed Cognition

Cognitive processes can be distributed across a group of individuals in a social group

It can involve coordinated interaction between those individuals and elements of their environment

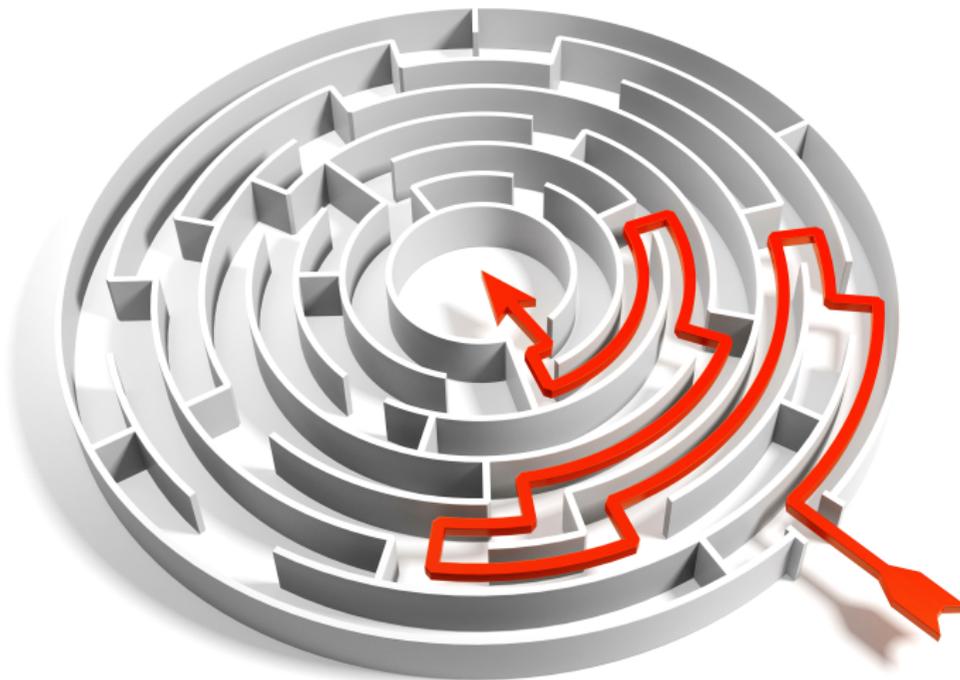
Distributed over resources, space, and time

Social organizations are cognitive

E. Hutchins. Cognition in the Wild. MIT Press, Cambridge, MA, 1995.

Cognition	Necessary Constituents	Typical Characteristics
Embodied	Depends on interpretation	Body and brain are both constitutive elements of the cognitive process
Situated	Brain	Real-time interaction with the environment
Embedded	Brain, body	Exploit the environment and other agents to assist with cognitive activities
Grounded	Brain and body	Experiential modal representations and internal simulation
Extended	Brain, body, environment	Environment is part of the cognitive system
Distributed	Brain, body, environment	Cognitive systems include environmental systems

Embodiment



Historical embodiment
Physical embodiment
Organismoid embodiment
Organismic embodiment
Social embodiment
Mechanistic embodiment
Phenomenal embodiment

Embodiment



Embodied cognition
Situated cognition
Embedded cognition
Grounded cognition
Extended cognition
Distributed cognition



Navigating the Mazes of Autonomy and Embodiment in Cognitive Systems

David Vernon
University of Skövde
Sweden

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5 October 2013